#### WORLD METEOROLOGICAL ORGANIZATION

#### COMMISSION FOR BASIC SYSTEMS

#### OPEN PROGRAMME AREA GROUP ON INTEGRATED OBSERVING SYSTEMS

# EXPERT TEAM ON REQUIREMENTS AND IMPLEMENTATION OF AWS PLATFORMS (ET-AWS) (Seventh Session)

Geneva, Switzerland 16-20 April 2012

**FINAL REPORT** 

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#### **GENERAL SUMMARY**

#### 1. ORGANIZATION OF THE SESSION

#### 1.1 Opening of the session

1.1.1 The Seventh Session of the CBS Expert Team on Requirements and Implementation of AWS Platforms (ET-AWS) was held in Geneva, Switzerland from 16 to 20 April 2012. The meeting was opened by Mr Karl Monnik, Chair of ET-AWS. Mr Monnik welcomed all participants (listed at Annex I); both those attending in Geneva and those participating remotely by electronic conferencing.

#### 1.2 Adoption of the agenda

1.2.1 The Session adopted the modified <u>Agenda</u> for the meeting, which is reproduced on p. iii of this report.

#### 1.3 Working arrangements

1.3.1 The tentative working hours for the meeting were agreed upon.

#### 2. REPORT OF THE CHAIRMAN

2.1 The Chair of ET-AWS, Mr Monnik, reported on the ET's activities since 2010 and on the achievements against the approved work plan to date. Mr Monnik noted that the previous meeting of ET-AWS was held 22-25 June 2010 in Geneva (see <a href="http://www.wmo.int/pages/prog/www/OSY/Reports/ET-AWS-6">http://www.wmo.int/pages/prog/www/OSY/Reports/ET-AWS-6</a> Geneva 2010 REV.doc). Since the meeting the composition of ET-AWS has changed and is currently made up of the following members:

1. MONNIK, Karl	Chair	Australia	RAV
2. MERROUCHI, Rabia	Vice-chair	Morocco	RAI
3. PATERSON, Charles		Canada	RAIV
4. FENG, Dongxia		China	RAII
5. KRISHNAIAH, Sevakula	a	India	RAII
6. VAN DER MEULEN, Jit	ze	Netherlands	Representing CIMO
7. CERVENA, Eva		Czech Republic	Representing IPET-DRC
8. SABATINI, Francesco		Italy	Representing CgAM

- 2.2 ET-AWS-6 considered the contribution of ET-AWS to WIGOS. The ET-AWS work plan includes elements which contribute towards WIGOS goals through facilitating interoperability, standardisation, and management of metadata and data discovery. Further progress is required before ET-AWS can contribute meaningfully to WIGOS, particularly considering the increasing role AWSs play in National networks.
- 2.3 It was agreed during ET-AWS-6 that AWS Functional Specifications should be continuously maintained and reviewed. To improve the process of maintaining and updating Functional Specifications, ET-AWS agreed that proposed variables should have a "mentor" on a semi-permanent basis. The Functional Requirements were accepted by ICT-IOS.
- 2.4 Considering the important role of data communications for AWS networks, ET-AWS-6 had endorsed a proposal originating as a recommendation from the JCOMM Pilot Project for WIGOS to establish an international forum of users of satellite data telecommunication systems to address system deficiencies, negotiate tariffs and potential improvements of the rendered

services with the operators of satellite data telecommunication systems. The proposal was supported by ICT-IOS-6, agreed during CBS-Ext(2010) and presented to Cg-XVI.

- 2.5 Cg-XVI supported the establishment of the proposed international forum of users of satellite data telecommunication systems covering a wide user base, to address, inter alia, remote data communication requirements including tariff negotiations as needed for automatic environment observing systems coordinated through WMO and partner organizations such as IOC and FAO. In considering the proposal, Cg-XVI expressed concern regarding the fact that data from many Antarctic stations funded by research agencies are not available in real-time and, therefore, are not available to NWP systems. It noted that the high communication cost involved in using Iridium satellites is also a limiting factor. Congress requested the Executive Council and the Secretary-General, in collaboration with CBS and JCOMM, to investigate possible ways to reduce such costs through the proposed forum. It also expressed its desire that WIS would provide a suitable environment for collection and dissemination of data from research observing stations. The first SATCOM workshop has been scheduled for the week following ET-AWS-7 and ET-AWS will be represented at the meeting by its Chair.
- 2.6 Following input by both ET-AWS and ET-ST&MT, guidance material concerning the transition from manual to automated observations was presented to CIMO. This document requires some further review before it can be published.
- 2.7 An exploratory proposal by ET-AWS to consider the potential of surface-based AWS hosted sensors being used to validate satellite observations was considered by CBS ET-SAT and ET-SUP. Following consideration at ICT-IOS-6, and discussion at ET-SAT-6 and subsequent action taken by EUMETSAT and its Land Surface Analysis SAF, clear interest in AWS measurements of the following variables was identified:
- DWSF (Downward Surface Shortwave Flux)
- DSLF (Downward Surface Longwave Flux)
- - LST (Land Surface Temperature)
- AL (Earth Surface Albedo)

ET-AWS-7 will need to consider how best to take this forward. Sites where this is already measured, or could potentially be measured, will need to be identified.

- 2.8 The siting classification scheme, which was proposed in ET-AWS-5 and further expanded in ET-AWS-6, was endorsed by CIMO-XV in Helsinki, 2010. CIMO-XV requested it to be included in the CIMO Guide with the following clarifications in order to ensure its appropriate use: 1) the use of the siting classification of observing stations depends on the purposes of the observations, 2) the proposed classification is the first official version of the siting classification, and will be reviewed and updated as needed at CIMO-XVI. The classification was published in Annex IV of CIMO-XV (WMO No. 1064) and is about to be published in the latest edition of the CIMO Guide, which is expected to be accessible very soon on the CIMO website.
- 2.9 CIMO also requested guidance material to be developed on the characterisation process for stations and advice on how to use the results obtained, indicating for which purpose stations of a specific class are appropriate.
- 2.10 AWSs continue to expand across the globe, including in most NHMS. The need for requirements and standards for robust AWSs suitable for less developed and remote areas is a priority for WMO. These requirements should highlight the ongoing need for site visits and skills required to manage such networks.
- 2.11 Cooperation with IPET-DRC has continued with further revision of some the BUFR/CREX descriptors for the functional specifications for AWS. Terminology for radiation still needs to be resolved. BUFR descriptors for all the variables defined in the AWS Functional Specifications have been developed. Where necessary IPET DRC have developed and validated new descriptors. The BUFR template for n-minute AWS data was expanded to include ground

temperature over a variety of surfaces following a request made during the third meeting of IPET-DRC.

#### 3 DEVELOPMENT AND IMPLEMENTATION OF THE WIGOS CONCEPT

- 3.1 Dr Atkinson provided a brief history of the development of the WIGOS concept and described recent progress in the development and implementation of the WIGOS draft Implementation Plan.
- 3.2 Cg-XVI (Geneva, May-June 2010), through its resolution (Res. 50 (Cg-XVI) Implementation of the WMO Integrated Global Observing System (WIGOS), decided to implement the WMO Integrated Global Observing System. It further decided that implementation activities will be undertaken during the next financial period as one of the major efforts of the Organization with the goal that WIGOS should become operational from 2016 onwards. Cg-XVI provided overall guidance and determined responsibilities for all constituent bodies to ensure WIGOS implementation. The tasks assigned by Congress to technical commissions are of direct relevance to the ET-AWS as one of the working bodies of CBS.
- 3.3 Cg-XVI in particular requested the technical commissions to:
  - Guide the technical aspects of WIGOS implementation;
  - Incorporate WIGOS implementation activities in their operating plan and work programme;
  - Provide technical guidance and advice to Members and the regional associations on WIGOS;
  - Develop guidance for the design and evolution of observing components of WIGOS;
  - Develop standards to support WIGOS in collaboration with partner organizations and programmes;
  - Update WMO Regulatory Material, including development of the Manual on WIGOS;
  - Provide the technical lead for WIGOS through the Commission for Basic Systems (CBS) and the Commission for Instruments and Methods of Observation (CIMO).
- 3.4 Congress emphasized that the implementation of WIGOS should build upon and add value to the existing WMO observing systems with emphasis on integration of surface- and space-based observations in an evolutionary process to satisfy requirements of WMO and WMO co-sponsored Programmes. Congress noted that, since all WMO Programmes would benefit, each should actively participate and contribute its own expertise and resources in implementing WIGOS.
- 3.5 Congress recognized the important role of WIS in WIGOS implementation, in relation to data exchange and discovery, and the provision of effective standards and practices for data management. Congress stressed the importance of coordination between WIGOS and WIS implementation activities.
- 3.6 Congress stressed the importance of the development of an implementation plan for the evolution of WIGOS beyond 2015 including technical guidance on how to design, develop and implement integrated national observing systems to provide comprehensive observations in response to the needs of all WMO Members and Programmes.
- 3.7 Congress agreed that the implementation of WIGOS must be reflected in the revised WMO Technical Regulations, documenting the WIGOS concept of operations and contributions of all observing components. In this regard, the Congress endorsed the inclusion of the Manual on WIGOS in the list of mandatory publications. Following the decision by Cg-XVI, EC-LXIII (May, 2011) established the Inter-Commission Coordination Group on WIGOS (ICG-WIGOS) under the chairmanship of Mr Fred R. Branski (USA), the president of CBS, with representatives of regional associations and international partner organizations during the

implementation process. ICG-WIGOS was specifically tasked to develop and submit the WIGOS Implementation Plan (WIP) for approval by the EC-64.

- 3.8 The first session of the ICG-WIGOS was held at the WMO Secretariat in Geneva, Switzerland, from 26 to 30 September 2011.
- 3.9 Based on the decisions by Cg-XVI and EC-LXIII, ICG-WIGOS-1 addressed all key components of WIGOS implementation:
  - WIGOS Concept of Operations Functional Architecture;
  - Manual on WIGOS:
  - WIGOS Communications and Outreach Strategy;
  - WIGOS Capacity Building Strategy;
  - WIGOS Implementation Plan (WIP);
  - Guidance on WIGOS activities to be implemented by Members.
- 3.10 ICG-WIGOS formulated recommendations and guidance on the above WIGOS implementation components<sup>1</sup> and established, inter-alia, the following Task Teams (TT): TT on WIGOS Manual, TT on WIGOS Metadata and TT on WIGOS Implementation Plan (WIP).
- 3.11 The Task Team on WIP (TT-WIP) met in Geneva from 27 to 30 March 2012 under the chairmanship of F. Branski and developed a draft WIP, version 0.8 (see Appendix I) which will be submitted to EC-64 for approval through the document EC-64/Doc. 4.4(1).
- 3.12 In elaborating the WIP, TT-WIP-1 addressed major technical issues, and made appropriate changes/edits to ensure full compliance with the guidance and recommendations made by Cg and EC. Table 4.1 of the draft WIP presents the description of implementation activities, associated deliverables, timelines, responsibilities, costs and associated risk
- 3.13 Particular attention of ET-AWS was invited to the Key Activity Areas for WIGOS Implementation described in the draft WIP. It was recommended that for each activity a detailed activity plan be developed by the responsible entity(s) with support of the Project Office and guidance from ICG-WIGOS. ET-AWS was invited to indicate to the WIGOS Project Office those activities to which it could contribute.
- 3.14 Following the task on further alignment of programme activities to support WIGOS implementation, a proposal for the possible new structure of CBS OPAG-IOS (2012-2016) was developed jointly by the Secretariat with the President of CBS and the Chair and Co-chair of OPAG IOS. The Meeting was invited to provide comment to ICT-IOC through the Chair of ET-AWS on the suggested new structure of OPAG-IOS, keeping in mind that there would be a need to focus the OPAG's limited resources during the coming inter-sessional period to assist with WIGOS Implementation whilst maintaining its priority activities at an acceptable level.
- 3.15 Dr Lars Peter Riishojgaard (chair of ICT-IOS) and Dr Wenjian Zhang (Director Observing and Information Systems) joined the ET meeting to discuss options for the future configuration of the ETs under IOS following CBS XV. The clear goal for all Teams will be the implementation of WIGOS. Hence it is important that the teams and work plans are reconfigured to ensure that they contribute towards this goal. Following earlier discussions between ICT-IOS chair, co-chair and the Director of Observing and Information Systems, a draft proposal which would add a Task Team (TT) on WIGOS Metadata and amalgamate ET-AWS and ET-SBROS had been presented. On the one hand, there is a clear need to reduce the number of ETs, but on the other hand there was little common ground between the members of ET-SBRSO and ET-AWS. However there was potential compatibility in areas such as metadata and meteorological coding using BUFR. The discussion emphasised that elements of all ETs that would contribute most to WIGOS were cross-cutting, such as

<sup>&</sup>lt;sup>1</sup> Final report of the ICG-WIGOS-1 is available at <a href="http://www.wmo.int/pages/prog/www/WIGOS-WIS/reports.html">http://www.wmo.int/pages/prog/www/WIGOS-WIS/reports.html</a>

metadata, manuals and implementation plan. Considering the key contributions AWSs make in both current and future networks, and the important tasks for both teams in terms of WIGOS, ET-AWS suggests that AWS expertise be retained as an entity, with active contribution in the cross-cutting activities. However, the pressure on the WMO secretariat is noted.

3.16 Following a meeting with WIS TT ApMD-1, (discussed in Section 8), ET-AWS identified the value of developing a future task to enhance Volume A in support of WIS. This would contribute strongly to WIGOS through the Operational database and provide the interface to WIS Metadata for AWS and site, station and data processing related metadata.

### 4 REQUIREMENTS FOR THE INTEGRATION BETWEEN AWS AND SPACE-BASED OBSERVATIONS

- 4.1 The meeting was joined by Jerome Lafeuille (WMO Sat Program) and Mr Michael Kalb (Chair ET-SAT) for the discussion concerning the integration between surface and spaced-based observations. ET-AWS proposed using surface-based observations to contribute to the validation of remotely sensed observations, such as sensors based on satellite platforms. The Vision for the Global Observing System 2025 states that the surface-based GOS will provide data for the calibration and validation of space-based observations. This is inline with the concept of WIGOS. ET-SAT together with EUMETSAT and its Land Surface SAF expressed interest AWS measurements and suggested four variables for a pilot study.
- 4.2 Recognising that modern AWS platforms are able to record, process and transmit observations from a wide range of electronic sensors and these networks have a global reach which covers all continents and climates, they provide an opportunity for integration and data validation. However, comparison between the Surface-based and Space-based system is difficult due to the scale differences. Of greatest value are surface-based sites representing large homogeneous areas.
- 4.3 ET-AWS proposes to pursue a pilot study to identify observations sites which measure the parameters highlighted by ET-SAT and EUMETSAT. ET-AWS will develop guidelines for meteorological observations which may support spaced-based observations including functional specifications, reporting formats and message distribution requirements.
- 4.4 Mr Lafeuille noted that the satellite community welcomed the initiative of ET-AWS and they recognised the potential benefit to both systems. ET-SAT was interested in the location of stations which currently measure the four variables mentioned earlier. In addition, surface fluxes of CO<sub>2</sub>, which were often spatially consistent, would also be of great value. Dr van der Meulen noted that these variables should be part of the RRR database.

### 5 REQUIREMENTS AND SPECIFICATIONS FOR AUTOMATED OBSERVATIONS NETWORKS

- 5.1 One of the tasks of the ET-AWS is to develop and maintain the requirements and specifications for automated observations networks. For this task the ET-AWS has focussed on the update of the table on Functional Specifications of ET-AWS variables (the FS table) that appears in Annex III.1 of the Guide to the GOS (WMO No. 488, 2010 ed.) and the table of observational variables, as required for a standard AWS (Annex III.2 of the Guide to the GOS). The further development of requirements and specifications for automated observations networks was not considered within the context of network design. Nevertheless it was noted that automation and standardization will provide interesting opportunities to find network design solutions, which is not possible in cases of networks based on manned stations. Alternatively, more suitable locations with better siting conditions, or remote areas can be chosen. Moreover an AWS is more flexible in replacement or relocation, in the case of modification of networks to support requests of users for temporary changes (e.g. relocation during a particular season).
- 5.2 The meeting considered proposed changes to the FS table. Many changes were already

considered during the previous session of ET-AWS in 2010 (see Final Report of ET-AWS-6). Since then some BUFR descriptors have been tested and validated, so are now ready for operational implementation. An updated table was considered by the meeting and is now recommended for adoption by the next CBS session as a replacement in the Guide to the GOS (see Annex II).

- 5.3 It was noted that additions and modifications have been suggested by the satellite and radiation communities within WMO. These modifications however still have to be prepared in detail. Because no input or comments on the modifications have been received from a number of Technical Commissions, it was proposed to request input for future modifications from the other OPAG-IOS teams as well the Presidents of these Commissions. It was noted that the ET-AWS-6 recommendation to nominate mentors, each to be responsible for keeping a certain category of variables up-to-date, had not resulted in further action to date.
- 5.4 The ET was informed on the WMO Observing Requirements Database with variables defined for the Rolling Requirements Review process (RRR), which is under review by ET-EGOS. It was noted that the table of variables, as stated in the table of functional requirements, should be in line with the list of variables published in this database (see <a href="http://www.wmo-sat.info/db/variables">http://www.wmo-sat.info/db/variables</a>).
- 5.5 ET-AWS agreed that the FS table should be continuously maintained and reviewed, i.e. to review the variables and requirements for measurement ranges and associated resolutions, by taking into consideration the changing needs of the various disciplines in meteorology, climatology and hydrology. Also the table in the Guide to the GOS containing the list of variables required to be measured by a Standard AWS should be maintained and reviewed in parallel.
- 5.6 Noting the range limitations of humidity sensors, yet the need for high quality data at the extremes of the humidity range, ET-AWS decided to request CIMO to evaluate by intercomparison the performance of different humidity measurement systems at the extreme ends of the temperature and humidity (<5% >95%) ranges.

### 6 REQUIREMENTS AND STANDARDS FOR A BASIC, ROBUST AWS SUITABLE FOR LESS DEVELOPED, REMOTE AND EXTREME CLIMATE CONDITIONS

- 6.1 Mr Krisnaiah informed the session of India's perspective on the requirements and standards for AWSs operating in remote or under-developed regions, noting that these fall under several different broad groupings.
- 6.2 **Telecommunications**: GSM / GPRS mode of communication for AWS data transmission is cheaper than Satellite communication. These networks are now available almost everywhere in many less developed countries. GPRS transmission equipment (GPRS modems) and receiving systems are much cheaper as compared to satellite systems. GPRS networks may be used wherever they are available whereas satellite communications (such as FY-DCP and BEIDOU, in China's case) have been used where GSM/GPRS networks are unavailable.
- 6.3 **Power requirements**: Solar panels attached with a battery are a useful power source for AWS at remote areas. Solar panels and batteries are easily available and quite affordable in many less developed regions. It was noted during the meeting that China has investigated the use of wind turbines at some sites and plans to use these where there is a shortage of solar power.
- 6.4 **Sensors**: Mr Krisnaiah suggested that robust and high quality sensors are required for remote areas. Sensors and the platform employed should be suitable for remote diagnostics and troubleshooting in order to avoid frequent inspection visits. Sensors with integral redundant elements can also be considered so that repair trips are minimised.

- 6.5 **AWS equipment**: The cost of the data loggers and communication equipment has come down drastically with recent advances in electronics technologies. However equipment which can work in extended temperature ranges are still expensive. Robust data loggers and communication equipment are required which can work in extreme environments of, e.g., temperature and humidity.
- 6.6 **AWS** cabinets: In extreme weather areas cabinets should be rust proof and salt resistant. These enclosures should be preferably of non-metal construction so that inside temperature does not increase considerably, causing malfunction of electronic equipment or batteries. In tropical areas rain fall rates can be very high, causing water incursion. Cabinets also need to be suitably designed so that connector exposure to the environment is minimal.
- 6.7 **Radiation shields:** Mr Krisnaiah stated that, based on the experience of the India Meteorological Department, radiation shields should be rugged and allow representative ambient temperature to be experienced over the sensors, so wooden or plastic Stevenson screens of the size specified by WMO should be employed in place of some currently-used plastic shields.
- 6.7 **Maintenance free earthing**: In tropical areas AWS equipment is often damaged because of lightning strikes. Conventional earthing provided at an AWS site can become ineffective in a short period of time unless it is regularly maintained. Maintenance-free earthing (especially of the chemical type) could be very effective in the long run and does not need frequent trips to AWS site. State-of-the-art lightning arrestors together with maintenance-free earthing at the site could reduce AWS faults due to lightning.
- 6.8 **Calibration of sensors and maintenance of stations:** Tropical regions have peculiar problems in maintenance of AWS sensors due to dust deposition. Calibration of sensors should be performed at least once in a year. Preventive maintenance is required to be undertaken once in every quarter. Availability of manpower and funds are major constraints in accomplishing these tasks.
- 6.9 **Upkeep and maintenance**: Though AWS are generally unmanned by design, regular visits to a site are required to check its security, exposure conditions and for performing preventive maintenance. The costs of maintenance, calibration and running expenses for an operating AWS network far outweigh the initial purchase expense, so these expenses should be kept in mind before planning installation of an AWS network.
- 6.10 **Site Security:** At remote regions especially in less developed countries, security of AWS equipment at sites has become a major concern. It is seen that there are many thefts of solar panels and batteries from the AWS sites. The general public has come to know that solar panels and batteries can be used in other domestic applications. Because of this, there can be significant numbers of thefts and cases of vandalism at AWS sites. Public participation and awareness programmes can help to reduce thefts and vandalism as can involvement of the general public in safe keeping the sites, particularly once they are informed of the usefulness of these systems for their day to day lives. Other solutions to the security problem are still being sought. The participation of Non Governmental Organisations (NGO) can be considered.

### 7 GAP ANALYSIS FOR AUTOMATED OBSERVATIONS FOLLOWING THE TRANSITION FROM MANUAL OBSERVATIONS

7.1 There was no finalised report available on the subject of the Gap Analysis on moving from manual to automatic observations; there had been a report previously prepared that was not deemed ready for publication. The ET considered the possibility of encouraging a volunteer to complete the document, but due to the impending deadline of submission to ICT-IOS in the lead up to CBS-XV, it was decided that is now impractical. Although the modernisation and increasing automation of networks was becoming ubiquitous among many NMHSs, the preparation of such a gap analysis document could be useful in planning for the

consequences of migrating to automatic observations, though this guidance may not influence their decisions to migrate. ET-AWS will therefore seek further guidance from ICT-IOS on the required focus of the document before assigning a future priority to this task.

7.2 It was noted that are two different gaps to be addressed, should the task be reassigned to ET-AWS. The first is a capability gap due to the inability of current automated observations to be able to detect human observed characteristics (e.g. cloud type). The second type is a business gap; factoring in the costs of maintaining the equipment, retraining of current staff, or dealing with site security.

#### 8 AWS METADATA CATALOGUES FOR REAL-TIME EXCHANGE THROUGH WIS

- 8.1 Discussion of this topic commenced with Mr. Paterson recounting some of his experiences with metadata as part of overall data management in the Meteorological Service of Canada (MSC). This involves both static metadata (defined for this purpose as stored and generally updated manually) and more dynamic metadata that has been transmitted as part of data transmissions. An important precedent was set in the MSC in 2004-2006 when road weather metadata was initially defined in XML to transmit with each observation every 20 minutes, but eventually due to the volume of data and the redundancy of the transmissions was changed to occurring in weekly updates. This change produced much smaller files to be transmitted but there have been some metadata refresh problems since then, even with simplified metadata requirements..
- 8.2 Work with metadata in data transmission in MSC goes back to the mid-1990s with the use of quality assessment BUFR descriptors in a limited manner within the data transmitted from staffed and automatic surface stations. More recent work involves transmissions from a major partner using instrumentation metadata captured in BUFR Table D descriptor 3 01 091 and quality tables (Table B 33 class). This provides a limited selection of metadata about 3<sup>rd</sup>-party stations but internal users are looking for more than that.
- 8.3 ET-AWS listed some required metadata, in a non-exhaustive list. These include both relatively static and more changeable values, such as:
  - Instrumentation including type and model;
  - Inspection types, reasons, and dates with associated sensor changes, in short a change and maintenance log of the site;
  - Whether sensors were in or out of service;
  - Height of instruments (generally some of this metadata is currently provided);
  - Distance of sensors from datalogger (or site layout);
  - Site photographs:
  - Datalogger program version;
  - Algorithms used for calculating derived data (whether at site or downstream) and whether data is derived or measured;
  - Siting classifications;
  - Quality assessment flags;
  - Quantitative uncertainty.
- 8.4 Dr. van der Meulen pointed out that we have existing standards on AWS metadata which are referenced in the Guide to the GOS and the Manual on the GOS. It was also noted that, although it was not an encouraged practice to put a lot of metadata in transmissions on the GTS, we are obliged, as part of existing BUFR templates, to provide some metadata. A key issue noted is that even if one makes a major effort to update metadata whenever possible, it will become out-of-date unless there are ways of both providing timely updates to metadata and also refreshing all metadata, to avoid the repository becoming stale. Procedures could range from updates and periodic refreshes in observations on the GTS to periodic distribution of bundles of metadata.

- 8.5 To address this issue, it was raised during the joint session of ET-AWS and the first session of the WIS Task Team on Applications of Metadata (WIS TT ApMD-1), conducted on Wednesday 18 April 2012. At that session it was established that the interface between the two teams would primarily be through Volume A, and that TT ApMD would require ET-AWS to provide a specification of requirement for AWS network-related metadata.
- 8.6 To further address the issue, a brief review of the "Guide to GOS, section III (Surface-Based subsystem) Appendix III Automatic Station Metadata" was performed to ascertain that the document was current and provided sufficient detail. It was found to provide good detail but required some review. ET-AWS agreed to recommend to ICT-IOS that this task be pursued.
- 8.7 Finally, a brief examination of the gap analysis in "Space-Based GOS in 2010" (<a href="http://www.wmo.int/pages/prog/sat/gos-dossier\_en.php">http://www.wmo.int/pages/prog/sat/gos-dossier\_en.php</a>) was performed. Similar to the AWS, the satellite is a platform with sensors attached serving multiple sets of clients. Although there are key differences, such as the much greater number of AWS platforms and their greater heterogeny, this document provided useful guidance to ET-AWS.

### 9 GUIDELINES FOR THE SITING CLASSIFICATION OF SURFACE OBSERVING STATIONS

- 9.1 The siting classification which was proposed in ET-AWS-5 and further expanded in ET-AWS-6 was endorsed by CIMO-XV in Helsinki, 2010. The Commission has requested that it be included in the CIMO Guide with the following clarifications in order to ensure its appropriate use: i) the use of the siting classification of observing stations depends on the purposes of the observations, ii) the proposed classification is the first official version of the siting classification, and will be reviewed and updated as needed at the next CIMO. The classification was published in Annex IV of CIMO-XV (WMO No. 1064). The Commission requested that guidance material on the characterisation process for stations and advice on how to use the results obtained, indicating for which purpose stations of a specific class are appropriate, needs to be developed.
- 9.2 The Meteorological Service of Canada (MSC) is looking to applying the Météo-France siting classifications to Canadian stations. Mr. Bill Scott (MSC) is undertaking this work during this year and is applying it to existing sites; minor modifications needed to be made since the sites were not green field sites. There is no initial intention to upgrade the siting at the time of evaluation, but MSC will build up its metadata of siting classification and may propose that certain sites be upgraded where feasible such as designated reference sites. A few minor changes have been made to the classification; the siting classification of the Tipping-Bucket Rain Gauge was placed in a new section called Rainfall Intensity, and new sections have been added for Precipitation Wind (wind at precipitation sensor level) and for Snow Depth. The Maintenance Performance (A to E) part of the classification will be done at a later stage since the MSC wishes to use an internationally-accepted standard.
- 9.3 ET-AWS recognised that a classification regarding the level of maintenance would be valuable and supported efforts by CIMO to develop this.

#### 10 BUFR DESCRIPTORS RELATED TO AWS

#### 10.1 BUFR/CREX descriptors related to AWS

- 10.1.1 The 14th Session of the Commission for Basic Systems (Dubrovnik, Croatia, 25 March to 2 April 2009) reviewed the Functional Specifications for Automatic Weather Stations and adopted draft Recommendation 6.1/2 (CBS-XIV).
- 10.1.2 Dr Eva Červená submitted a document to ET-AWS-6 (Geneva, 22 to 25 June 2010), containing detailed analysis of the requirements for representation of the listed variables, a revised version of the Functional Specifications for AWS and a proposal for several new

BUFR/CREX descriptors. ET-AWS-6 examined carefully these proposals, agreed with the proposed new BUFR/CREX descriptors and procedures for representation of the listed variables, and suggested some modifications of the requirements.

- 10.1.3 The Second meeting of the Inter-Programme Expert Team on Data Representation and Codes (IPET-DRC) approved the proposed or modified BUFR/CREX descriptors for validation. The ET AWS members were encouraged to participate actively in the validation process of the proposed new descriptors.
- 10.1.4 In 2011, BUFR messages were created in the Czech Hydrometeorological Institute (CHMI) using the encoding/decoding software of CHMI and ECMWF. These messages contained extreme values of the elements as requested in the Functional Specifications for AWS, which documented the capability of the validated descriptors to meet the requirements. The validation process led to changing the specification for "Soil heat flux"; no other requirements had been expressed by the ET-AWS. Consequently the descriptors included in Annex III were submitted to the Third meeting of the IPET-DRC that recommended them for the fast-track procedure (with the implementation date of 2 May 2012).
- 10.1.5 The radiation terminology was discussed and the meeting decided to accept the names of BUFR/CREX descriptors Class 14 as they are, provided that they are unambiguous.

#### 10.2 Template for n-minute data (TM 307092)

- 10.2.1 At the Third meeting of the IPET DRC (IPET DRC-III, Melbourne, 20 to 23 September 2011), the UKMO announced their plans to use the n-minute template (TM 307092) as a way of introducing higher temporal resolution data for ingestion into its forecast models. The existing template had had provision for only one ground temperature over the primary surface type for the station, whereas the UKMO record ground temperatures over a variety of surfaces at many of the observing stations (on grass, concrete and road/runways). A new surface type element was added to the existing Code table 0 08 010 (12 = Concrete). IPET DRC-III meeting consequently modified the existing template TM 307092 to allow reporting measurements of ground temperature at more than one point, and recommended this template for further validation.
- 10.2.2 The ET-AWS-7 meeting examined this version of TM 307092 and requested the possibility to report temperature and wind data at several heights above ground (mast measurements). Regarding ground temperature, the height above local ground should be considered as a variable. Dr Červená modified the template to meet these requirements as shown in Annex IV. This updated version of TM 307092 will be submitted to the IPET DRC-IV meeting (Exeter, 21 to 25 May 2012).
- 10.2.3 The ET-AWS-7 meeting invited members of ET AWS to participate in validation of templates TM 307092 (as well as template TM 307093 for representation of nominal values).

#### 10.3 Specification of the station location in the CIMO Guide

10.3.1 Dr Červená pointed out different requirements for specification of station location in various WMO documents. The station location is specified in all BUFR descriptors for AWS data by latitude (0 05 001) and longitude (0 06 001) in degrees with resolution of 10<sup>-5</sup> of a degree. The height of the station above mean sea level (0 07 030) is specified in meters, with a resolution of a tenth of a meter. In the Manual on the GOS (WMO-No. 544) and in WMO-No.9, Volume A, the location of stations is requested in degrees, minutes and seconds; and height of the station above mean sea level, H, is requested in meters rounded to two decimals. However, the definition of station coordinates in the Guide to the GOS (WMO-No.488) and the CIMO Guide (Seventh Edition of 6 August 2008) do not meet the current requirements for specification of station location. Moreover, the specification of the location to which the horizontal coordinates refer, is not sufficiently defined.

10.3.2 The ET AWS-7 meeting recommended unifying the reporting of station location in WMO documents so that latitude and longitude of a station are given in degrees with a resolution of 10<sup>-4</sup> of a degree or better and the height of the station above mean sea level is given in metres, with a resolution one metre or better. Moreover, the specification of the location to which the horizontal coordinates refer, should be more precisely defined.

#### 11 ADVANCES IN AWS TECHNOLOGY

#### 11.1 Progress and Advances

- 11.1.1 Dr. Sabatini described how the main advance in AWS technology relates to telemetry, especially through increased flexibility of choice (radio, satellite, GSM, GPRS, LAN). Another advance includes a decrease in cost of sensors and data loggers. Either of these may lead to reduction in required battery capacity and solar panel dimensioning. However, despite the generally decreasing trend of the cost of data transmission, telecommunications services costs can remain high because cheaper options are not available in some locations. In this context Dr Sabatini remarked on the successful work of CBS and JCOMM to establish an International Forum of Users of Satellite Data Telecommunication Systems together with IOC and FAO partner international organizations. A preparatory workshop in Toulouse, France, 23-24 April 2012 has been planned to bring forward these topics.
- 11.1.2 The requirements for new data loggers mainly relate to high flexibility in signal input type; analogue, digital, serial RS232, serial SDI-12. Serial inputs allows data acquisition of multiple devices that normally lead also to lowering power requirements and make room for additional input sensors. Wireless technology is increasingly being exploited to build up a dense sensor network based on small data loggers with specific radio interfaces (433 MHz, 868 MHz, ZigBee 2.4 GHz). Many applications relate to precision agriculture, hydrology, monitoring systems for renewable energy.
- 11.1.3 Even when remote data transmission is configured, first level quality checks could be implemented, but these cannot replace local inspection. Allocation of sufficient funds for Information Technology (IT) personnel and electronics specialists is necessary to properly manage modern AWS networks. The integration between GIS and Sensor Web Enablement (SWE) approach needs to be highlighted. There are increasing numbers of online sensors. Standardization of sensors metadata is a requirement for handling observations and information for different sensors. The Open Geospatial Consortium (OGC) SWE standards meet this requirement and provide open source platforms for a series of applications. Sensor spatial location is usually a key piece of sensor or sensor data information, as well as other related information (Manufacturer, Model Type, data of installation) and SWE standards make it easy to integrate this information into geospatial applications that implement the OGC's other standards.
- 11.1.4 In 2009 WMO signed a Memorandum Of Understanding (MOU) with the OGC. This agreement has been promoted in order to "enhance the development and use of geospatial standards. It is anticipated that this collaboration will support the implementation of the WMO Information System (WIS) which aims at providing a single coordinated global infrastructure for the collection and sharing of information in support of all WMO and related international programmes. The MoU formalizes the partners' planned collaboration in the development, application, and promotion of standards and best practices for the content and exchange of meteorological, climatological and hydrological data for the benefit of the worldwide scientific and operational communities of meteorologists and hydrologists".
- 11.1.5 The WMO Secretariat appointed the Inter-Programme Expert Team on Metadata and Data Interoperability (IPET-MDI), to "develop a WMO core profile of the ISO 191 series of standards for metadata and data, encompassing the WMO Metadata core profile of the ISO metadata standard, including relevant feature catalogues, application schema(ta) and data

product specification(s)". One of the main tasks assigned to this ET is to create sustainable data and metadata standards that meet the needs of WMO's stakeholder community. This should mean that the standards need to be: as simple as possible, based around standards already in use, supported by education and best practice guidance and with clear governance measures in place. This approach should facilitate the free and unrestricted exchange of data and information, products and services in real- or near-real time.

- 11.1.6 Another important initiative to be mentioned here relates to the activities of the International Organizing Committee for the WMO Solid Precipitation Inter-comparison Experiment (WMO IOC-SPICE coordinated by Ms Rodica Nitu (Canada) and Roy Rasmussen (USA). The Inter-comparison will focus on the performance of modern automated sensors measuring solid precipitation during the period of the year when the precipitation is expected to be solid. As a first priority, the WMO-SPICE will investigate and report on the measurement of precipitation amount as a function of precipitation phase, and of snow on the ground (snow depth), so it will be of interest to test the performance of different types of precipitation gauges, disdrometers, present weather and snow depth sensors. New models of weighing precipitation gauges have been developed in the last few years and this measuring principle is now widely accepted as the reference method, even though shielding is of primary interest. Another aspect relates to the heated versions of precipitation gauges, where the importance of the standardization of the heating algorithm should be addressed to the users.
- 11.1.7 ET-AWS proposed that the future work plan of the ET includes continued monitoring of technology advances for sensors, AWS technology and telemetry options, in order to promote awareness and discussion on this important topic.

#### 11.2 Guidance on Integration

- 11.2.1 Mr Monnik suggested that a common problem which impacts many modern meteorological organisations is how to effectively use and integrate data from external sources. There are costs associated with ingest, archival, monitoring and communications. Issues around intellectual property rights and obligations, relationship management and contract management all create an economic impost on the organisation.
- 11.2.2 To make an informed decision regarding use or investment in external data there are several areas that need to be considered. Fundamentally it needs to be determined how the data source delivers value to the organisation. This includes consideration of the spatial contribution the data/information makes to the organisation and the network benefits. The quantity, quality and currency of metadata will govern the usefulness of the data. If an adequate level of metadata is not available there may be no point in continuing to consider ingesting the external data. Reaching agreement on custodianship of data is important. The accessibility of the data in terms of delivery, formats and method is a further criterion which should be considered. The final step is an agreement to manage the relationship in the long term. The steps involved in this process are discussed further in Annex V, which is based on information provided to the Chair of ET-AWS by Dr Jane Warne of the Bureau of Meteorology in Australia and further developed by the members of ET-AWS during the session.
- 11.2.3 ET-AWS 6 considered guidance for managing AWS networks. In addition to this, the ET proposed a series of steps to consider in integrating observations coming from different networks, particularly from third party AWS networks:
  - Define a minimum set of information (range, reported accuracy, height of sensors, metadata, etc.) and procedures (regular inspections, maintenance, etc.) required to integrate observations
  - Collect as much information as possible about the configuration of the third party network, such as: technical features, calibration sheets, manuals, algorithms employed, shields (i.e. for air Temperature and Humidity), in order to define the limits within which the observations of such AWSs can be roughly collocated.

- Check and report suggested corrections to third party AWS network configurations, if deficiencies are highlighted which may limit the use of those observations.
- Inter-comparison testbeds should be established at which to evaluate the performance of such systems against well proved AWSs already in use, in different weather conditions for several years
- The degree of the integration of observations is different for each variable. For example temperature sensors are generally quite robust even if they belong to lowcost systems, while relative humidity sensors are intrinsically more fragile; in this case a large source of error comes from poorly designed shields. Wind speed sensors made of poor construction tend to have perform badly especially at low wind speed.
- When we use cost-effective AWSs the general approach is to replace damaged sensors instead of opening a repair procedure. Normally the interchangeability of these sensors is not well defined, even if digital sensors nowadays offer more quarantees. In this case acceptance limits can be defined.
- Remote operational status monitoring allows early detection of failures or suspect values and should be encouraged.
- 11.2.4 There are other aspects of third party data capture that warrant consideration. The growing availability of external observations combined with the growing number of users of social networks and smart phone devices, suggest to the scientific community new possibilities for third party data communications. Third party sensor intercomparisons would assist in better characterizing the data from these instruments.

#### 12 OTHER BUSINESS

#### 12.1 ET-AWS input to ET-EGOS on EGOS-IP

- 12.1.1 ET-AWS welcomes the Implementation Plan for the Evolution of the Global Observing Systems considering the significant advances being made in both surfaced-based and particularly space-based systems. The surface-based systems generally provide traceable and temporally consistent observations which are an important historically consistent baseline for all observations systems.
- 12.1.2 ET-AWS noted that AWS networks continue to expand across many countries, including third party automated networks. These networks require an investment in data handling, technical capacity and management which should be considered when embarking on such network changes. Clear standards for the surface observing system should be upheld in the manual for the GOS so that a composite, integrated observation network is maintained.

#### 12.2 Input to upcoming SatCom meeting (Toulouse, 23-24 April 2012)

- 12.2.1 Considering the important role of data communications for AWS networks, ET-AWS-6 endorsed a proposal originating as a recommendation from the JCOMM Pilot Project for WIGOS to establish an international forum of users of satellite data telecommunication systems that could to address system deficiencies, negotiate tariffs and potential improvements of the rendered services with the operators of satellite data telecommunication systems. Such a forum could partner with International Organizations such as FAO and IOC. This was supported by ICT-IOS-6, agreed during CBS-Ext(2010) and presented to Cg-XVI.
- 12.2.2 The first meeting of this forum is scheduled for May 2012 and ET-AWS, represented by its chair, will describe the needs for cost-effective data communication in remote area where land based telecommunications networks are unavailable.

#### 12.3 Regulatory Material for AWS

12.3.1 It was noted that the requirements and specifications for automated observations networks, inclusive functional requirements of the specific observational variables and the table of variables to be observed by a standard AWS are published as guidelines only (i.e. in the Guide to the GOS). The Manual to the GOS, however, provides standards, inclusive of the set of variables to be reported from e.g. Synoptic AWS. The ET suggested ICT-IOS to consider moving these guidelines into the Manual, because these requirements can be considered as standard requirements.

#### 12.4 AWS Data Quality Control

12.4.1 The following identified gaps require further attention of the ET-AWS: With the advances of AWS, an important problem in need of addressing and therefore for the future attention of ET-AWS, is the quality control of AWS data, so a document about AWS data quality control algorithms, in particular precipitation algorithms, is required to promote reliability and consistency of data.

#### 13 RECOMMENDATIONS FOR CBS-XV

13.1 ET-AWS-7 drafted one recommendation for consideration by the next meeting of ICT-IOS and submission to CBS-XV, concerning adoption of the updated Functional Specification for AWS and its publication in the Guide to the GOS. This draft recommendation is at Annex VI.

#### 14 WORK PLAN

- 14.1 ET-AWS-7 referred to the work plan for the closing inter-sessional period, considered which items needed further attention and new times for inclusion, and proposed those items listed in Annex VII to be included in the future work plan of the group..
- 14.2 ET-AWS-7 also proposed modified Terms of Reference for the new group, which are contained in Annex VIII.

#### 5 CLOSURE OF THE SESSION

10.1 The session was closed on 20 April 2012 at 1700h.

#### **ANNEX I**

#### **LIST OF PARTICIPANTS**

Mr Karl MONNIK  Mr Rabia MERROUCHI (teleconference)	Bureau of Meteorology G.P.O. Box 1289 Melbourne, Vic 3001 Australia Tel.: +(61 3) 9669 4205 Fax: +(61 3) 9669 4168 E-mail: k.monnik@bom.gov.au  Direction de la Météorologie Nationale, CNME/SMM BP 8106 en face de la prefecture Hay Hassani Casablanca Morocco Tel.: +(212 522) 90 20008 Fax: +(212 522) 90 8593
Mr Charles PATERSON	E-mail: rabia.merrouchi@gmail.com  Meteorological Service of Canada 4905 Dufferin Street Toronto Ontario M3H 5T4 Canada Tel.: +(1 416) 739 4485
	Fax: +(1 416) 739 5721 E-mail: charles.paterson@ec.gc.ca
Mr Sevakula KRISHNAIAH (teleconference)	India Meteorological Department Ganeshkhind Road Shivaji Nagar Pune 411 005 India Tel.: +(91 20) 2553 5411 Fax: +(91 20) 2552 1529 E-mail: krishnasya@gmail.com
Dr Jitze P. van der MEULEN Representing CIMO	Royal Netherlands Meteorological Institute Wilhelminalaan 10 P.O.Box 201 NL-3730 AE de BILT Netherlands Tel.: +(31 30) 220 6432 Fax: +(31 30) 221 0407 E-mail: Jitze.van.der.Meulen@knmi.nl
Ms FENG Dongxia Invited Expert	China Meteorological Administration No. 46 Zhongguacun, Nandajie Beijing 100081 China Tel.: +(86 10) 6840 6421 Fax: +(86 10) 6217 8786 E-mail: fengdx@cma.gov.cn
Dr Eva ČERVENÁ	Czech Hydrometeorological Institute

	Na Sabatce 17
Invited Expert	Praha-4 14306
	Czech Republic
	Tel: + 4202 4403 22 15
	Fax: + 4202 4403 22 35
	E-mail: cervena@chmi.cz
Dr Francesco SABATINI	CNR-IBIMET
	Institute of Biometeorology
Representing CAgM	Via Giovanni Caproni, 8
	50145 Florence
(teleconference)	Italy
	Tel1.: +(39) 055 303 3711
	Tel2.: +(39) 055 5226029
	Fax: +(39) 055 308 910
	f.sabatini@ibimet.cnr.it
Mr Tom Copping	Business Development Manager
in rom copping	Fairmount Weather Systems
Representing HMEI	UK
Troprocenting Times	Tel: +44 1763 263 415
	Mob :: +44 7715 395 190
	E-mail: tom@fairmountweather.com
Ms Johanna Rämö	Application Manager
	Meteorology, Surface Observations
Representing HMEI	Vaisala Oyj.
	P.O.Box 26
	FIN 00421 Helsinki
	Finland
	<b>Finland</b> Tel: + 358-9-8949 2508
	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726
	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568
	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com
	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568
WMO SECRETARIAT	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com
WMO SECRETARIAT 7 bis. avenue de la Paix	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com
WMO SECRETARIAT 7 bis, avenue de la Paix CH-1211 Geneva 2	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website
7 bis, avenue de la Paix	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com
7 bis, avenue de la Paix CH-1211 Geneva 2	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html
7 bis, avenue de la Paix CH-1211 Geneva 2	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278 Fax: +41 22 730 8021
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278 Fax: +41 22 730 8021
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON  Dr Isabelle RÜEDI	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  Www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278 Fax: +41 22 730 8021 E-mail: IRuedi@wmo.int
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON  Dr Isabelle RÜEDI	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278 Fax: +41 22 730 8021 E-mail: IRuedi@wmo.int  Chief, OSD Tel.: +41 22 730 8409 Fax: +41 22 730 8021
7 bis, avenue de la Paix CH-1211 Geneva 2 Switzerland  Dr Roger ATKINSON  Dr Isabelle RÜEDI	Finland Tel: + 358-9-8949 2508 Mob: + 358-40-7371726 Telefax: + 358-9-8949 2568 E-mail: johanna.ramo@vaisala.com http://www.vaisala.com  WWW Website  www.wmo.int/web/www/www.html  IMO Section, OSD Tel.: +41 22 730 8011 Fax: +41 22 730 8021 E-mail: Ratkinson@wmo.int Head, IMO Section, OSD Tel.: +41 22 730 8278 Fax: +41 22 730 8021 E-mail: IRuedi@wmo.int  Chief, OSD Tel.: +41 22 730 8409

#### **ANNEX II**

Functional Specifications for Automatic Weather Stations (NOTE: Updated table entries and notes are shown in bold text)

(NOTE: Opua	ited table entries a		IOWII III DOIC	i (ext)	
VARIABLE 1)	Maximum Effective Range <sup>2)</sup>	Minimum Reported Resolution <sup>3)</sup>	Mode of Observation <sup>4)</sup>	BUFR / CREX <sup>5)</sup>	Status <sup>5)</sup>
ATMOSPHERIC PRESSURE					
Atmospheric Pressure	500 – 1080 hPa	10 Pa	I, V	0 10 004	OP
TEMPERATURE 9)					
Ambient air temperature (over specified surface) 14)	-80 °C – +60 °C	0.1 K	I, V	0 12 101	OP
Dew-point temperature <sup>14)</sup>	-80 °C – +60 °C	0.1 K	I, V	0 12 103	OP
Ground (surface) temperature (over specified surface) 14)	-80 °C – +80 °C	0.1 K	I, V	0 12 120	VAL
Soil temperature <sup>14)</sup>	-50 °C – +50 °C	0.1 K	I, V	0 12 130	OP
Snow temperature <sup>14)</sup>	-80 °C – 0 °C	0.1 K	I, V	0 12 131	VAL
Water temperature - river, lake, sea, well	-2 °C – +100 °C	0.1 K	I, V	0 13 082 or <b>0 22 043</b>	OP OP
HUMIDITY 9)					
Relative humidity	0 – 100%	1%	I, V	0 13 003	OP
Mass mixing ratio	0 – 100%	1%	I, V	0 13 110	VAL
Soil moisture	$0 - 10^3 \mathrm{g  kg^{-1}}$	1 g kg <sup>-1</sup>	I, V	0 13 111	VAL
Water vapour pressure	0 – 100 hPa	10 Pa	I, V	0 13 004	OP
Evaporation/evapotranspiration	0 <b>– 0.25</b> m	0.1 kg m <sup>-2</sup> 0.0001 m	Т	<b>2 01 130</b> 0 13 033 <b>2 01 000</b>	ОР
Object wetness duration	0 – 86 400 s	1 s	Т	0 13 112	VAL
WIND					
Direction	0 <sup>11,13)</sup> ; 1° – 360°	1°	I, V	0 11 001	OP
Speed	0 – 75 m s <sup>-1</sup>	0.1 m s <sup>-1</sup>	I, V	0 11 002	OP
Gust Speed	0 – 150 m s <sup>-1</sup>	0.1 m s <sup>-1</sup>	I, V	0 11 041	OP
X,Y component of wind vector Z component of wind vector (horizontal and vertical profile)	-150 - 150 m s <sup>-1</sup> -40 - 40 m s <sup>-1</sup>	0.1 m s <sup>-1</sup>	I, V	0 11 003 0 11 004 0 11 006	OP OP OP
Turbulence type (Low levels and wake vortex) 16)	up to 15 types	BUFR Table Not specified yet	I, V	-	N
Turbulence intensity <sup>16)</sup>	up to 15 types	BUFR Table Not specified yet	I, V	-	N
RADIATION 6)		ус			
Sunshine duration	0 – 86 400 s	60 s	Т	0 14 031	OP
Background luminance	<b>0 – 1·10</b> <sup>5</sup> Cd m <sup>-2</sup>	1Cd m <sup>-2</sup>	I, V	0 14 056	VAL
Global downward solar radiation	0 – <b>1·10</b> <sup>8</sup> J m <sup>-2</sup>	<b>1. 10<sup>2</sup></b> J m <sup>-2</sup>	I, T, V	0 14 028	OP
Global upward solar radiation	<b>-1·10<sup>8</sup> – 0</b> J m <sup>-2</sup>	<b>1. 10<sup>2</sup></b> J m <sup>-2</sup>	I, T, V	0 14 052	VAL
Diffuse solar radiation	<b>0 – 1·10</b> <sup>8</sup> J m <sup>-2</sup>	<b>1. 10<sup>2</sup></b> J m <sup>-2</sup>	I, T, V	0 14 029	OP
Direct solar radiation	<b>0 – 1·10</b> <sup>8</sup> J m <sup>-2</sup>	<b>1. 10<sup>2</sup></b> J m <sup>-2</sup>	I, T, V	0 14 030	OP
Downward long-wave radiation	<b>0 – 6·10</b> <sup>7</sup> J m <sup>-2</sup>	<b>1. 10<sup>3</sup></b> J m <sup>-2</sup>	I, T, V	0 14 002	OP
Upward long-wave radiation	<b>-6·10<sup>7</sup> – 0</b> J m <sup>-2</sup>	<b>1. 10<sup>3</sup></b> J m <sup>-2</sup>	I, T, V	0 14 002	OP
Net radiation	-1·10 <sup>8</sup> - 1·10 <sup>8</sup> J m <sup>-2</sup>	<b>1. 10<sup>2</sup></b> J m <sup>-2</sup>	I, T, V	0 14 053	VAL
UV-B radiation 8)	<b>0 – 26·10</b> <sup>4</sup> J m <sup>-2</sup>	<b>1</b> J m <sup>-2</sup>	I, T, V	0 14 072	VAL
Photosynthetically active radiation <sup>22)</sup>	0- <b>6·10</b> <sup>7</sup> J m <sup>-2</sup>	<b>1·10</b> <sup>3</sup> J m <sup>-2</sup>	I, T, V	0 14 054	VAL
Surface albedo	0 – 100%	1% 1. 10 <sup>2</sup> J m <sup>-2</sup>	I, V	0 14 019	OP
Soil heat Flux	-1·10 <sup>8</sup> – 1·10 <sup>8</sup> J m <sup>-2</sup>		I, T, V	0 14 057	VAL

Cloud base height	CLOUDS					
Cloud top height		0 – 30 km	10 m	I. V	0 20 013	OP
Dougle to the properties of the pypes   Up to 30 classes   BUFR Table   I   0 20 012   OP						
Sypes						
Effective radius of cloud   2-10-5 - 32-10-5 m   2-10-5 m   2-10-5 m   1-10-5 kg m <sup>-3</sup>   1.V   0.20 131   VAL   Optical depth within each layer   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not specified yet   1, V   - N   Not specified yet   Not spe	types	•		· ·	0 20 012	OF
hydrometeors		dm <sup>-3</sup>	1 hydrometeor dm <sup>-3</sup>	I, V	0 20 130	VAL
Optical depth within each layer         Not specified yet         Not specified yet         I, V         -         N           Optical depth of fog         Not specified yet         Not specified yet         I, V         -         N           Height of inversion         0 - 1 000 m         10 m         I, V         0 20 093         VAL           Cloud cover         0 - 100%         1%         I, V         0 20 010         OP           Cloud amount         0 - 8/8         1/8         I, V         0 20 011         OP           PRECIPITATION         0 - 1600 mm         0.1 kg m², 0.0001         T         0 13 011         OP           Depth of fresh snowfall         0 - 1000 cm         0.001 m         T         0 13 118         VAL           Duration         up to 86 400 s         60 s         T         0 26 020         OP           Size of precipitating element <sup>170</sup> 1 · 10³ - 0.25 m         1 · 10³ m         I, V         0 13 158         OP           Intensity - quantitative         0 - 2000 mm h¹         0 · 1 kg m² s³.         I, V         0 13 155         OP           Type         up to 30 types         BUFR Table         I, V         0 20 021         OP           Hydrometeor type         up to 30 types </td <td></td> <td>2·10<sup>-5</sup> – 32·10<sup>-5</sup> m</td> <td></td> <td>I, V</td> <td>0 20 131</td> <td>VAL</td>		2·10 <sup>-5</sup> – 32·10 <sup>-5</sup> m		I, V	0 20 131	VAL
Optical depth of fog         Not specified yet         I, ∨         -         N           Height of inversion         0 − 1 000 m         10 m         I, ∨         0 20 093         VAL           Cloud cover         0 − 100%         1%         I, ∨         0 20 010         OP           PRECIPITATION         Accumulation 7)         0 − 1600 mm         0.1 kg m², 0.0001 m m         T         0 13 011         OP           Depth of fresh snowfall         0 − 1000 cm         0.001 m m         T         0 13 118         VAL           Duration         up to 86 400 s         60 s         T         0 26 020         OP           Size of precipitating element 170         1.10³ − 0.25 m         1.10³ m l, ∨         0 213 058         OP           Intensity - quantitative         0 − 2000 mm h¹         0.1 kg m² s¹         I, ∨         0 213 058         OP           Type         up to 30 types         BUFR Table         I, ∨         0 20 021         OP           Rate of ice accretion         0 − 1 kg dm²² h¹         1.10³ kg dm² h¹         I, ∨         0 20 025         OP           Phydrometeor type         up to 30 types         BUFR Table         I, ∨         0 20 025         OP           Hydrometeor type         up to 30 types	Cloud liquid water content	1·10 <sup>-5</sup> –1.4·10 <sup>-2</sup> kg m <sup>-3</sup>	1·10 <sup>-5</sup> kg m <sup>-3</sup>	I, V	0 20 132	VAL
Height of inversion	Optical depth within each layer	Not specified yet	Not specified yet	I, V	-	N
Cloud cover	Optical depth of fog	Not specified yet	Not specified yet	I, V	-	N
Cloud amount	Height of inversion	0 – 1 000 m	10 m	I, V	0 20 093	VAL
PRECIPITATION	Cloud cover	0 – 100%	1%	I, V	0 20 010	OP
Accumulation   7    0 - 1600 mm   0.1 kg m², 0.0001 m   T   0 13 011   OP	Cloud amount	0 – 8/8	1/8	I, V	0 20 011	OP
Depth of fresh snowfall   D - 1000 cm   Depth of fresh snowfall   Duration   Up to 86 400 s   Go s   T   O 26 020   OP	PRECIPITATION					
Depth of fresh snowfall	Accumulation 7)	0 <b>– 1600 mm</b>		Т	0 13 011	OP
Duration         up to 86 400 s         60 s         T         0 26 020         OP           Size of precipitating element <sup>177</sup> 1·10³ − 0.25 m         1·10³ m         I, V         0 13 058 020 066         OP           Intensity - quantitative         0 − 2000 mm h⁻¹         0.1 kg m² s⁻¹, 0.1 mm h⁻¹         I, V         0 13 155         OP           Type         up to 30 types         BUFR Table         I, V         0 20 021         OP           Rate of ice accretion         0 − 1 kg dm² h⁻¹         1·10³ kg dm² h⁻¹         I, V         0 20 021         OP           Rate of ice accretion         0 − 1 kg dm² h⁻¹         1·10³ kg dm² h⁻¹         I, V         0 20 025         OP           Rate of ice accretion         0 − 1 kg dm² h⁻¹         1·10³ kg dm² h⁻¹         I, V         0 20 025         OP           Rate of ice accretion         0 − 1 kg dm² h⁻¹         1·10³ kg dm² h⁻¹         I, V         0 20 025         OP           Bacter of ice accretion         0 − 1 kg dm² h⁻¹         1·10³ kg dm²² h⁻¹         I, V         0 20 025         OP           BUSCRATIONS         0         Up to 30 types         BUFR Table         I, V         0 20 025         OP           Lightroneteor type         up to 30 types         BUFR Table         I, V	Depth of fresh snowfall	0 –1000 cm		Т	0 13 118	VAL
Size of precipitating element   17   1.10   3   0.25 m	•	up to 86 400 s	60 s	Т	0 26 020	OP
Intensity - quantitative	Size of precipitating element <sup>17)</sup>			I, V		ОР
Rate of ice accretion         0 − 1 kg dm² h¹         1 ⋅ 10³ kg dm² h¹         I, V         0 13 114         VAL           OBSCURATIONS           Obscuration type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Hydrometeor type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Lithometeor type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Hydrometeor radius         2⋅10⁻⁵ – 32⋅10⁻⁵ m         2⋅10⁻⁵ m         I, V         0 20 033         VAL           Extinction coefficient         0 − 1 m⁻¹         0.00001 m⁻¹         I, V         0 15 029         VAL           Meteorological Optical Range ¹¹o¹         1 − 100 000 m         1 m         I, V         0 15 051         VAL           Runway visual range         1 − 4 000 m         1 m         I, V         0 20 061         OP           Other weather type         up to 18 types         BUFR Table         I, V         0 20 023         OP           Lightning rates of discharge         0 − 4 500 000 h⁻¹         1 h⁻¹         I, V         0 20 126         VAL           Lightning discharge type (cloud to surface)         3 types         BUFR Code Table	Intensity - quantitative	0 – 2000 mm h <sup>-1</sup>	0.1 kg m <sup>-2</sup> s <sup>-1</sup> , 0.1 mm h <sup>-1</sup>	I, V		ОР
OBSCURATIONS         up to 30 types         BUFR Table         I, V         0 20 025         OP           Hydrometeor type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Lithometeor type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Hydrometeor radius         2 · 10 · 5 · 32 · 10 · 5 m         2 · 10 · 5 m         I, V         0 20 133         VAL           Extinction coefficient         0 - 1 m · 1         0.00001 m · 1         I, V         0 15 029         VAL           Meteorological Optical Range <sup>10)</sup> 1 - 100 000 m         1 m         I, V         0 15 051         VAL           Runway visual range         1 - 4 000 m         1 m         I, V         0 20 061         OP           Other weather type         up to 18 types         BUFR Table         I, V         0 20 023         OP           Lightning rates of discharge         up to 18 types         BUFR Table         I, V         0 20 023         OP           Lightning discharge type (cloud to surface)         3 types         BUFR Code Table         I, V         0 20 023         OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 127 <t< td=""><td>Туре</td><td>up to 30 types</td><td>BUFR Table</td><td>I, V</td><td>0 20 021</td><td>OP</td></t<>	Туре	up to 30 types	BUFR Table	I, V	0 20 021	OP
Obscuration type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Hydrometeor type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Lithometeor type         up to 30 types         BUFR Table         I, V         0 20 025         OP           Hydrometeor radius         2:10-5-32:10-5 m         2:10-5 m         I, V         0 20 133         VAL           Extinction coefficient         0 - 1 m <sup>-1</sup> 0.00001 m <sup>-1</sup> I, V         0 15 029         VAL           Meteorological Optical Range <sup>10)</sup> 1 - 100 000 m         1 m         I, V         0 15 051         VAL           Runway visual range         1 - 4 000 m         1 m         I, V         0 20 061         OP           Other weather type         up to 18 types         BUFR Table         I, V         0 20 023         OP           Lightning rates of discharge         0 - 4 500 000 h <sup>-1</sup> 1 h <sup>-1</sup> I, V         0 20 126         VAL           Lightning discharge type (cloud to cloud, cloud to surface)         3 types         BUFR Code Table         I, V         0 20 123         OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 127	Rate of ice accretion	0 – 1 kg dm <sup>-2</sup> h <sup>-1</sup>	1·10 <sup>-3</sup> kg dm <sup>-2</sup> h <sup>-1</sup>	I, V	0 13 114	VAL
Hydrometeor type	OBSCURATIONS					
Lithometeor type	Obscuration type	up to 30 types	BUFR Table	I, V	0 20 025	OP
Hydrometeor radius	Hydrometeor type	up to 30 types	BUFR Table	I, V	0 20 025	OP
Extinction coefficient	Lithometeor type	up to 30 types	BUFR Table	I, V	0 20 025	OP
Meteorological Optical Range         10   1 - 100 000 m         1 m         I, V         0 15 051   VAL           Runway visual range         1 - 4 000 m         1 m         I, V         0 20 061   OP           Other weather type         up to 18 types         BUFR Table         I, V         0 20 023   OP           Lightning         Up to 18 types         BUFR Code Table         I, V         0 20 126   VAL           Lightning discharge type (cloud to surface)         3 types         BUFR Code Table         I, V         0 20 023   OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 119   VAL           Lightning discharge energy         Not specified yet         Not specified yet   I, V         - N           Lightning - distance from station         0 - 2·10 <sup>5</sup> m         10 <sup>3</sup> m         I, V         0 20 127   VAL           Lightning - direction from station         1° - 360°   1 degree         I, V         0 20 128   VAL           HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge - well         0 - 2.5·10 <sup>5</sup> m³ s⁻¹   0.1 m³ s⁻¹   I, V         0 23 040   VAL           Flow discharge - well         0 - 1 800 m   0.01 m³ s⁻¹   I, V         0 23 041   VAL           Ground water level         0 - 1 800 m   0.01 m   I, V         0 13 074   VAL	Hydrometeor radius		2·10 <sup>-5</sup> m	I, V	0 20 133	VAL
Runway visual range	Extinction coefficient	0 – 1 m <sup>-1</sup>	0.00001 m <sup>-1</sup>	I, V	0 15 029	VAL
Other weather type         up to 18 types         BUFR Table         I, V         0 20 023         OP           Lightning rates of discharge         0 - 4 500 000 h <sup>-1</sup> 1 h <sup>-1</sup> I, V         0 20 126         VAL           Lightning discharge type (cloud to cloud, cloud to surface)         3 types         BUFR Code Table         I, V         0 20 023         OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 119         VAL           Lightning discharge energy         Not specified yet         Not specified yet         I, V         -         N           Lightning - distance from station         0 - 2·10 <sup>5</sup> m         10 <sup>3</sup> m         I, V         0 20 127         VAL           Lightning - direction from station         1° - 360°         1 degree         I, V         0 20 128         VAL           HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge - river         0 - 2.5·10 <sup>5</sup> m <sup>3</sup> s <sup>-1</sup> 0.1 m <sup>3</sup> s <sup>-1</sup> I, V         0 23 040         VAL           Flow discharge - well         0 - 50 m <sup>3</sup> s <sup>-1</sup> 0.001 m <sup>3</sup> s <sup>-1</sup> I, V         0 23 041         VAL           Ground water level         0 - 1 800 m         0.01 m         I, V         0 12 132         VAL	Meteorological Optical Range 10)	1 – 100 000 m	1 m	I, V	0 15 051	VAL
Lightning rates of discharge         0 − 4 500 000 h⁻¹         1 h⁻¹         I, V         0 20 126         VAL           Lightning discharge type (cloud to cloud, cloud to surface)         3 types         BUFR Code Table         I, V         0 20 023         OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 119         VAL           Lightning discharge energy         Not specified yet         Not specified yet         I, V         - N           Lightning - distance from station         0 - 2·10⁵ m         10³ m         I, V         0 20 127         VAL           Lightning - direction from station         1° - 360°         1 degree         I, V         0 20 128         VAL           HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge - river         0 - 2.5·10⁵ m³ s⁻¹         0.1 m³ s⁻¹         I, V         0 23 040         VAL           Flow discharge - well         0 - 50 m³ s⁻¹         0.001 m³ s⁻¹         I, V         0 23 041         VAL           Ground water level         0 - 1 800 m         0.01 m         I, V         0 13 074         VAL           Lightning discharge energy         Not specified yet         I, V         0 23 040         VAL	Runway visual range	1 – 4 000 m	1 m	I, V	0 20 061	OP
Lightning rates of discharge         0 - 4 500 000 h <sup>-1</sup> 1 h <sup>-1</sup> I, V         0 20 126         VAL           Lightning discharge type (cloud to cloud, cloud to surface)         3 types         BUFR Code Table         I, V         0 20 023         OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 119         VAL           Lightning discharge energy         Not specified yet         Not specified yet         I, V         -         N           Lightning - distance from station         0 - 2·10 <sup>5</sup> m         10 <sup>3</sup> m         I, V         0 20 127         VAL           Lightning - direction from station         1° - 360°         1 degree         I, V         0 20 128         VAL           HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge - river         0 - 2.5·10 <sup>5</sup> m <sup>3</sup> s <sup>-1</sup> 0.1 m <sup>3</sup> s <sup>-1</sup> I, V         0 23 040         VAL           Flow discharge - well         0 - 50 m <sup>3</sup> s <sup>-1</sup> 0.001 m <sup>3</sup> s <sup>-1</sup> I, V         0 23 041         VAL           Ground water level         0 - 1 800 m         0.01 m         I, V         0 13 074         VAL           lce surface temperature         -80 °C - +0 °C         0.5 K         I, V         0 12 132         VAL	Other weather type	up to 18 types	BUFR Table	I, V	0 20 023	OP
Lightning discharge type (cloud to cloud, cloud to surface)  Lightning discharge polarity  2 types  BUFR Code Table  I, V  0 20 023  OP  Lightning discharge polarity  2 types  BUFR Code Table  I, V  0 20 119  VAL  Lightning discharge energy  Not specified yet  Not specified yet  I, V  Not specified yet  I, V  Not specified yet  I, V  O 20 127  VAL  Lightning - distance from station  1° - 360°  1 degree  I, V  0 20 127  VAL  HYDROLOGIC AND MARINE  OBSERVATIONS  Flow discharge – river  0 - 2.5·10 <sup>5</sup> m³ s⁻¹  0.1 m³ s⁻¹  1, V  0 23 040  VAL  Flow discharge – well  0 - 50 m³ s⁻¹  0.001 m³ s⁻¹  I, V  0 23 041  VAL  Ground water level  0 - 1 800 m  0.01 m  I, V  0 13 074  VAL  lce surface temperature 14)  -80 °C - +0 °C  0.5 K  I, V  0 12 132  VAL	LIGHTNING					
to cloud, cloud to surface)         3 types         BOFR Code Table         I, V         0 20 023         OP           Lightning discharge polarity         2 types         BUFR Code Table         I, V         0 20 119         VAL           Lightning discharge energy         Not specified yet         Not specified yet         I, V         - N           Lightning - distance from station         0 - 2·10 <sup>5</sup> m         10 <sup>3</sup> m         I, V         0 20 127         VAL           Lightning - direction from station         1° - 360°         1 degree         I, V         0 20 128         VAL           HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge - river         0 - 2.5·10 <sup>5</sup> m³ s⁻¹         0.1 m³ s⁻¹         I, V         0 23 040         VAL           Flow discharge - well         0 - 50 m³ s⁻¹         0.001 m³ s⁻¹         I, V         0 23 041         VAL           Ground water level         0 - 1 800 m         0.01 m         I, V         0 13 074         VAL           lce surface temperature         -80 °C - +0 °C         0.5 K         I, V         0 12 132         VAL	Lightning rates of discharge	0 <b>– 4 500 000</b> h <sup>-1</sup>	1 h <sup>-1</sup>	I, V	0 20 126	VAL
Lightning discharge energy Not specified yet Not specified yet I, V - N Lightning - distance from station $0-2\cdot10^5\mathrm{m}$ $10^3\mathrm{m}$ I, V $020127$ VAL Lightning - direction from station $1^\circ-360^\circ$ $1\mathrm{degree}$ I, V $020128$ VAL HYDROLOGIC AND MARINE OBSERVATIONS  Flow discharge - river $0-2.5\cdot10^5\mathrm{m}^3\mathrm{s}^{-1}$ $0.1\mathrm{m}^3\mathrm{s}^{-1}$ I, V $023040$ VAL Flow discharge - well $0-50\mathrm{m}^3\mathrm{s}^{-1}$ $0.001\mathrm{m}^3\mathrm{s}^{-1}$ I, V $023041$ VAL Ground water level $0-1800\mathrm{m}$ $0.01\mathrm{m}$ I, V $013074$ VAL lce surface temperature $0.00\mathrm{m}$ $0.00\mathrm{m}$ I, V $0.00\mathrm{m}$ VAL $0.00\mathrm{m}$ I $0.00$		3 types	BUFR Code Table	I, V	0 20 023	OP
Lightning - distance from station $0-2\cdot10^5$ m $10^3$ m         I, V $0.20127$ VAL           Lightning - direction from station $1^{\circ}-360^{\circ}$ 1 degree         I, V $0.20128$ VAL           HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge - river $0-2.5\cdot10^5$ m³ s⁻¹ $0.1$ m³ s⁻¹         I, V $0.23040$ VAL           Flow discharge - well $0-50$ m³ s⁻¹ $0.001$ m³ s⁻¹         I, V $0.23041$ VAL           Ground water level $0-1800$ m $0.01$ m         I, V $0.12132$ VAL           Ice surface temperature $^{14)}$ $-80$ °C $-+0$ °C $0.5$ K         I, V $0.12132$ VAL	Lightning discharge polarity	2 types	BUFR Code Table	I, V	0 20 119	VAL
Lightning - direction from station $1^{\circ} - 360^{\circ}$ 1 degree       I, V       0 20 128       VAL         HYDROLOGIC AND MARINE OBSERVATIONS         Flow discharge - river $0 - 2.5 \cdot 10^{5} \text{ m}^{3} \text{ s}^{-1}$ $0.1 \text{ m}^{3} \text{ s}^{-1}$ I, V       0 23 040       VAL         Flow discharge - well $0 - 50 \text{ m}^{3} \text{ s}^{-1}$ $0.001 \text{ m}^{3} \text{ s}^{-1}$ I, V       0 23 041       VAL         Ground water level $0 - 1800 \text{ m}$ $0.01 \text{ m}$ I, V       0 13 074       VAL         Ice surface temperature $^{14}$ $-80  ^{\circ}\text{C} - +0  ^{\circ}\text{C}$ $0.5 \text{ K}$ I, V       0 12 132       VAL	Lightning discharge energy	Not specified yet	Not specified yet	I, V	-	N
HYDROLOGIC AND MARINE OBSERVATIONS           Flow discharge – river         0 - 2.5·10 <sup>5</sup> m³ s⁻¹         0.1 m³ s⁻¹         I, V         0 23 040         VAL           Flow discharge – well         0 - 50 m³ s⁻¹         0.001 m³ s⁻¹         I, V         0 23 041         VAL           Ground water level         0 - 1 800 m         0.01 m         I, V         0 13 074         VAL           Ice surface temperature 14)         -80 °C - +0 °C         0.5 K         I, V         0 12 132         VAL	Lightning - distance from station	0 <b>- 2·10</b> <sup>5</sup> m	10 <sup>3</sup> m	I, V	0 20 127	VAL
OBSERVATIONS           Flow discharge – river $0-2.5\cdot10^5$ m³ s⁻¹ $0.1$ m³ s⁻¹         I, V         0 23 040         VAL           Flow discharge – well $0-50$ m³ s⁻¹ $0.001$ m³ s⁻¹         I, V         0 23 041         VAL           Ground water level $0-1$ 800 m $0.01$ m         I, V         0 13 074         VAL           Ice surface temperature $-80$ °C $-+0$ °C $0.5$ K         I, V         0 12 132         VAL	Lightning - direction from station	1° – 360°	1 degree	I, V	0 20 128	VAL
Flow discharge – river $0-2.5\cdot 10^5  \text{m}^3  \text{s}^{-1}$ $0.1  \text{m}^3  \text{s}^{-1}$ I, V $0.23  040$ VAL Flow discharge – well $0-50  \text{m}^3  \text{s}^{-1}$ $0.001  \text{m}^3  \text{s}^{-1}$ I, V $0.23  041$ VAL Ground water level $0-1  800  \text{m}$ $0.01  \text{m}$ I, V $0.13  074$ VAL Ice surface temperature $0.01  \text{m}$ $0.01  \text{m}$ I, V $0.01  0.01  \text{m}$ I VAL $0.01$						
Flow discharge – well $0-50 \text{ m}^3 \text{ s}^{-1}$ $0.001 \text{ m}^3 \text{ s}^{-1}$ I, V $0.23 \text{ 041}$ VAL Ground water level $0-1.800 \text{ m}$ $0.01 \text{ m}$ I, V $0.13 \text{ 074}$ VAL Ice surface temperature $0.01 \text{ m}$ $0.01 \text{ m}$ I, V $0.012 \text{ 132}$ VAL		$0 - 2.5 \cdot 10^5 \mathrm{m}^3 \mathrm{s}^{-1}$	0.1 m <sup>3</sup> s <sup>-1</sup>	I, V	0 23 040	VAL
Ground water level         0 - 1 800 m         0.01 m         I, V         0 13 074         VAL           Ice surface temperature <sup>14)</sup> -80 °C - +0 °C         0.5 K         I, V         0 12 132         VAL	~					
lce surface temperature <sup>14)</sup> -80 °C - +0 °C 0.5 K I, V <b>0 12 132 VAL</b>		0 – 1 800 m	0.01 m		0 13 074	VAL
	Ice surface temperature 14)	-80 °C – +0 °C	0.5 K		0 12 132	VAL
Ice thickness - river, lake 15) 0 – 50 m 0.01 m I, V 0 8 029 0 13 115 VAL	Ice thickness - river, lake <sup>15)</sup>	0 – 50 m	0.01 m	I, V	0 08 029 0 13 115	VAL
Ice thickness - glacier, sea <sup>15)</sup> 0 – 4 270 m 1 m I, V 0 08 029 0 13 115 VAL	Ice thickness - glacier, sea 15)	0 – 4 270 m	1 m	I, V	0 08 029	VAL

	T			1	
Ice thickness <sup>18)</sup>	0 – 3 m	0.015 m	Т	2 01 133 2 02 129 0 20 031 2 02 000 2 01 000	ОР
Water level	0 – 100 m	0.01 m	I, V	0 13 071 0 13 072	OP OP
Wave height	0 – 50 m	0.1 m	V	0 22 021	OP
Wave period <sup>18)</sup>	0 – 100 s	1 s	V	<b>2 01 129</b> 0 22 011 <b>2 01 000</b>	ОР
Wave direction	0 <sup>13)</sup> ; <b>1</b> – 360 degrees	1 degree	V	0 22 001	OP
1D spectral wave energy density	0 – 5x10 <sup>5</sup> m <sup>2</sup> Hz <sup>-1</sup>	10 <sup>-3</sup> m <sup>2</sup> Hz <sup>-1</sup>	V, T	<b>2 01 135</b> 0 22 069 <b>2 01 000</b>	ОР
2D spectral wave energy density	0 – 5x10 <sup>5</sup> m <sup>2</sup> Hz <sup>-1</sup>	10 <sup>-3</sup> m <sup>2</sup> Hz <sup>-1</sup>	V, T	<b>2 01 135</b> 0 22 069 <b>2 01 000</b>	ОР
Water practical salinity <sup>18)</sup>	0 – 400 psu <sup>12</sup>	10 <sup>-3</sup> psu	I, V	2 01 130 0 22 064 2 01 000	ОР
Water conductivity <sup>18)</sup>	0 – 600 S m <sup>-1</sup>	10 <sup>-6</sup> S m <sup>-1</sup>	I, V	2 01 132 0 22 066 2 01 000	ОР
Water pressure <sup>18) 19)</sup>	0 – 11x10 <sup>7</sup> Pa	100 Pa	I, V	<b>2 07 001</b> 0 22 065 <b>2 07 000</b>	ОР
Ice mass	0 – 50 kg m <sup>-1</sup>	0.5 kg m <sup>-1</sup> (on 32 mm rod)	Т	0 20 135	VAL
Snow density (liquid water content)	100 – 700 kg m <sup>-3</sup>	1 kg m <sup>-3</sup>	Т	0 13 117	VAL
Tidal elevation with respect to local chart datum <sup>18)</sup>	-10 – +30 m	0.001 m	I, V	<b>2 01 129</b> 0 22 038 <b>2 01 000</b>	OP
Tidal elevation with respect to national land datum <sup>18)</sup>	-10 – +30 m	0.001 m	I, V	<b>2 01 129</b> 0 22 037 <b>2 01 000</b>	ОР
Meteorological residual tidal elevation (surge or offset) 18) 20)	-10 – +16m	0.001 m	I, V	0 22 040	OP
Ocean Current - Direction	0 <sup>13)</sup> ; 1° – 360°	<b>1°</b>	I, V	0 22 004 or 0 22 005	ОР
Ocean Current - Speed	0 – 10 m s <sup>-1</sup>	0.01 m s <sup>-1</sup>	I, V	0 22 031 or 0 22 032	OP
OTHER SURFACE VARIABLES					
Runway conditions	up to 10 types	BUFR Table	I, V	0 20 085	OP
Braking action/friction coefficient	up to 7 types	BUFR Table	I, V	0 20 089	OP
State of ground	up to 30 types	BUFR Table	I, V	0 20 062	OP
Type of surface specified	up to 15 types	BUFR Table	I, V	0 08 010	OP
Snow depth	0 – 25 m	0.01 m	T	0 13 013	OP
OTHER					
Gamma radiation dose rate <sup>12)</sup>	1 – 10 <sup>3</sup> nSv h <sup>-1</sup>	<b>0.1</b> nSv h <sup>-1</sup>	I, T	0 24 014	VAL
Categories of stability	9 types	BUFR Table	I, V	0 13 041	OP

#### **Notes:**

- 1. Name of variable, in line with WMO vocabulary and Technical Regulations.
- 2. Maximum Effective Range Maximum range of measuring capability; units traceable to SI.
- 3. Minimum Reported Resolution Lower resolution of reporting is not permitted.
- 4. Mode of Observation Type of data being reported:

- I: Instantaneous 1-minute value (instantaneous as defined in WMO-No. 8, Appendix VI.2);
- V: Variability Average (mean), Standard Deviation, Maximum, Minimum, Range, Median, etc. of samples those reported depend upon meteorological variable;
- T: Total Integrated value over defined period; maximum 24 hours for all parameters except radiation which requires a maximum of one hour (exception, see note 6), and precipitation accumulation (6 hours maximum). The relevant element descriptor shall be preceded by a time period descriptor 0 04 024 (in hours) or 0 04 025 (in minutes).
- A: Average (mean) value.
- 5. BUFR/CREX descriptors for representation of the listed variables;
  - OP: Operational descriptors of BUFR/CREX Table B, <u>Version Number 14 and subsequent versions</u>.

VAL: Descriptors which became operational on 2 May 2012 (BUFR/CREX Table B. Version Number 18).

- N: Not yet specified requirements.
- 6. Radiation energy amounts are given over a 24-hour period.
- 7. Liquid water equivalent. Maximum interval: 6 hours.
- 8. Definition of UV-B according to WMO-No. 8 (Vol. 1, Chapter on Radiation). Descriptor 0 14 072 (Global UV irradiation) was recommended for validation in September 2008, revised in July 2010.
- 9. Humidity related variables (*i.e.* dew point temperature) expressed as temperature are collected under temperature.
- 10. MOR uniquely related to "extinction coefficient",  $\sigma$ , by MOR =  $-\ln(5\%)/\sigma$ .
- 11. Direction to indicate 0 (zero) if speed = 0.
- 12. Absolute Salinity (kg.kg<sup>-1</sup>) is now being used for ocean applications (IOC Res XXV-7). However, salinity that is reported to national oceanographic data centres remains the Practical Salinity (psu). Ocean water is about 35 psu. Lake Assal (Djibouti) is the most saline body of water on earth with 348 psu salt concentration.
- 13. Calm.
- 14. Temperature data represented by 0 12 101, 0 12 103, 0 12 113, 0 12 120, 0 12 130, 0 12 131 and 0 12 132 shall be reported with precision in hundredths of a degree even if they are measured with the accuracy in tenths of a degree. This requirement is based on the fact that conversion from the Kelvin to the Celsius scale has often resulted into distortion of the data values. Temperature t (in degrees Celsius) shall be converted into temperature T (in degrees Kelvin) using equation: T = t + 273.15.
- 15. Ice thickness 0 13 115 shall be preceded by 0 08 029 (Surface type) set to 11, 12, 13 or 14 to specify river, lake, sea or glacier, respectively.
- 16. If the UNIT is specified as "BUFR Table", the BUFR descriptor cannot be proposed without the content of the table being available.
- 17. 0 13 058 (Size of precipitation element) is capable to express size of any precipitation element, apart from hailstones. Size of hailstones shall be represented by 0 20 066.
- 18. These requirements being confirmed, it has to be noted that the selected descriptors are suitable for the normal operating conditions and shall be combined with appropriate operator descriptors to allow representation of the extreme values or the requested high precision.
- 19. Operator 2 07 Y is recommended to be used with Water pressure 0 22 065 (Pa, -3, 0, 17), if the data are produced in BUFR, Edition 4. The same result, i.e. change to (Pa, -2, 0, 21) would be obtained by the combined use of the less sophisticated operators 201Y and 202Y:
  - 2 01 132
  - 2 02 129
  - 0 22 065 Reported value of "Water pressure"
  - 2 02 000
  - 2 01 000
- 20. The following sequence is to be used to change data width and reference value of 0 22 040 (m, 3, -5000, 14) to become (m, 3, -10000, 15):
  - 2 01 129
  - 2 03 015
  - 0 22 040 New reference value = -10000
  - 2 03 255

0 22 040 Reported value of "Meteorological residual tidal elevation"

- 2 01 000
- 2 03 000
- 21. Gamma radiation dose rate 0 24 014 is intended to be used for reporting of this element under normal conditions, nuclear accidents excluded.
- 22. Photosynthetically active radiation (PAR). Various forms of the electromagnetic energy flux in the 400 700 nm wavelength range, either as integrated spectra or using different weighting functions. For example converted to the photosynthetic photon flux (PPF) in quanta per second per square meter, or mole of quanta per second per square meter or microeinsteins per second per square meter. Approximate conversion is 1 J m<sup>-2</sup> s<sup>-1</sup> equivalent to 5 μE m<sup>-2</sup> s<sup>-1</sup> based on a mean wavelength of 550 nm.

#### **BUFR/CREX** to become operational on 2 May 2012

#### For Temperature

Table reference			BUFR				CREX	
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 12 120	Ground temperature	К	2	0	16	°C	2	4
0 12 131	Snow temperature	К	2	0	16	°C	2	4

#### **For Humidity**

Table reference	BUFR			BUFR				
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 13 110	Mass mixing ratio	%	0	0	7	%	0	3
0 13 111	Soil moisture	g kg <sup>-1</sup>	0	0	10	g kg <sup>-1</sup>	0	4
0 13 112	Object wetness duration	s	0	0	17	s	0	5

#### For Radiation

Table reference				BUFR		CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 14 052	Global upward solar radiation, integrated over period specified	J m <sup>-2</sup>	-2	-1048574	20	J m <sup>-2</sup>	-2	7
0 14 053	Net radiation (high accuracy), integrated over period specified	J m <sup>-2</sup>	-2	-1048574	21	J m <sup>-2</sup>	-2	7
0 14 054	Photosynthetically active radiation, integrated over period specified	J m <sup>-2</sup>	-3	0	16	J m <sup>-2</sup>	-3	5
0 14 056	Background luminance	Cd m <sup>-2</sup>	0	0	18	Cd m <sup>-2</sup>	0	6
0 14 057	Soil heat flux	J m <sup>-2</sup>	-2	-1048574	21	J m <sup>-2</sup>	-2	7
0 14 072	Global UV irradiation	J m <sup>-2</sup>	0	-4000000	23	J m <sup>-2</sup>	0	7
0 02 072	Spectrographic width	m	13	0	30	m	13	10

#### With a Note under Class 14:

(8) Global UV irradiation (0 14 072) is UV energy integrated over period specified for spectral band specified. 0 14 072 shall be preceded by a time period descriptor and by 0 02 071 (Spectrographic

wavelength) and 0 02 072 (Spectrographic width). E.g. If 0 14 072 is used for Global UV-B irradiation, 0 02 071 and 0 02 072 shall specify spectral band 280 to 315 nm.

#### For Clouds

Table reference		BUFR				CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 20 130	Cloud hydrometeor concentration	Numeric	0	0	10	Numeric	0	3
0 20 131	Effective radius of cloud hydrometeors	m	5	0	6	m	5	2
0 20 132	Cloud liquid water content	kg m <sup>-3</sup>	5	0	11	kg m <sup>-3</sup>	5	4
0 20 093	Height of inversion	m	-1	0	8	m	-1	3

#### With a Note under Class 20:

Cloud hydrometeor concentration 0 20 130 represents the number of hydrometeors in 1 dm<sup>3</sup>.

#### For Precipitation

Table reference		BUFR				CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 13 114	Rate of ice accretion	kg m <sup>-2</sup> h <sup>-1</sup>	1	0	11	kg m <sup>-2</sup> h <sup>-1</sup>	1	4
0 13 118	Depth of freshsnow (high accuracy)	m	3	-2	14	m	3	5

#### With a Note under Class 13:

Depth of fresh snow (0 13 118) set to -0.001 before scaling (-1 after scaling or in CREX) shall indicate a little snow (less than 0.0005 m). Depth of fresh snow (0 13 118) set to -0.002 before scaling (-2 after scaling or in CREX) shall indicate "snow cover not continuous".

The name of 0 20 032 is requested to be changed from the current "Rate of ice accretion" to "*Rate of ice accretion (estimated)*".

#### For Obscuration

Table reference		BUFR				CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 20 133	Hydrometeor radius	m	5	0	6	m	5	2
0 15 029	Extinction coefficient	m <sup>-1</sup>	9	0	30	m <sup>-1</sup>	9	10
0 15 051	Meteorological Optical Range	m	0	0	18	m	0	6

#### For Lightning

Table reference		BUFR				CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 20 126	Lightning rate of discharge	h <sup>-1</sup>	0	0	23	h <sup>-1</sup>	0	7
0 20 127	Lightning - distance from station	m	-3	0	8	m	-3	3
0 20 128	Lightning - direction from station	Degree true	1	0	12	Degree true	1	4
0 20 119	Lightning discharge polarity	Code table	0	0	2	Code table	0	1

#### 0 20 119 - Lightning discharge polarity:

Code figure	
0	Not defined
1	Positive
2	Negative
3	Missing value

#### For Hydrologic and marine data

Table reference			BUFR				CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width	
0 23 040	Flow discharge – river	m <sup>3</sup> s <sup>-1</sup>	1	0	22	$m^3 s^{-1}$	1	7	
0 23 041	Flow discharge – well	$m^3 s^{-1}$	3	0	16	$m^3 s^{-1}$	3	5	
0 13 074	Ground water level	m	2	0	18	m	2	6	
0 12 132	Ice surface temperature	К	2	0	16	°C	2	4	
0 13 115	Ice thickness	m	2	0	19	m	2	6	
0 20 135	Ice mass (on a rod)	kg m⁻¹	1	0	10	kg m <sup>-1</sup>	1	3	
0 13 117	Snow density (liquid water content)		0	0	10	kg m <sup>-3</sup>	0	3	

#### With a Note under Class 13:

Ice thickness 0 13 115 shall be preceded by 0 08 029 (Surface type) set to 11, 12, 13 or 14 to specify river, lake, sea or glacier, respectively.

The name of 0 08 029 has been changed to "Surface type" and the following code figures introduced:

#### 0 08 029 - Surface type:

Code figure

11 river

12 lake

13 sea14 glacier

### For Other

Table reference		BUFR				CREX		
FXY	Element name	Unit	Scale	Reference value	Data width	Unit	Scale	Data width
0 24 014	Gamma radiation dose rate	nSv h <sup>-1</sup>	1	0	14	nSv h⁻¹	1	4

#### With a Note under Class 24:

Gamma radiation dose rate 0 24 014 is intended to be used for reporting of this element under normal conditions, nuclear accidents excluded.

#### **ANNEX IV**

## BUFR template for surface observations from n-minute period TM 307092

National station identification	1 WI 307092			
0 01 101   State identifier (1)				Unit, scale
0 01 101	3 01 089		National station identification	
0 01 102		0 01 101		Code table, 0
Fixed surface station identification; time, horizontal and vertical co-ordinates				
	3 01 090			,
WMO block number   Numeric, 0				
WMO station number		3 01 004	Surface station identification	
Station or site name			WMO block number	Numeric, 0
Type of station			WMO station number	Numeric, 0
Month(2)   Day(2)   Day, 0			Station or site name	CCITT IA5, 0
Month(2)   Day(2)   Day, 0			Type of station	Code table, 0
Day/ <sup>2</sup>   Day, 0   Hour, 0   Hour, 0   Minute, 0   Degree, 5   Minute, 0   Degree, 5   Degree, 5  Degree, 5   Degree, 5   Degree, 5   Degree, 5   Degree, 5   Deg		3 01 011	Year <sup>(2)</sup>	Year, 0
3 01 012   Hour <sup>(2)</sup>   Minute <sup>(2)</sup>   Minute, 0			Month <sup>(2)</sup>	Month, 0
Minute, 0  3 01 021 Latitude (high accuracy)  Degree, 5  Longitude (high accuracy)  0 07 030 Height of station ground above mean sea level  0 07 031 Height of barometer above mean sea level  m, 1  0 08 010 Surface qualifier (for temperature data)  O 02 180 Main present weather detecting system  O 02 181 Supplementary present weather sensor  O 02 182 Visibility measurement system  O 02 183 Cloud detection system  Code table, 0  O 02 184 Type of lightning detection sensor  O 02 186 Capability to detect precipitation phenomena  O 02 187 Capability to detect other weather phenomena  O 02 188 Capability to detect obscuration  O 02 189 Capability to discriminate lightning strikes  O 02 189 Capability to discriminate lightning strikes  O 02 189 Capability to discriminate lightning strikes  O 04 015 Time increment (= - n minutes)  Minute, 0  Delayed replication of 32 descriptors  O 31 001 Delayed descriptor replication factor (= n)  Delayed descriptor replication factor  Numeric, 0  Wind data  O 07 033 Height of sensor above local ground  m 2  O 07 033 Height of sensor above water surface  m 1  O 11 004 Maximum wind gust direction  Degree true, 0  o 11 041 Maximum wind gust direction  Degree true, 0  Degree true, 0  Degree true, 0			Day <sup>(2)</sup>	Day, 0
3 01 021   Latitude (high accuracy)   Degree, 5		3 01 012		Hour, 0
Longitude (high accuracy)  0 07 030 Height of station ground above mean sea level  0 07 031 Height of barometer above mean sea level  0 08 010 Surface qualifier (for temperature data)  0 02 180 Main present weather detecting system  0 02 181 Supplementary present weather sensor  0 02 182 Visibility measurement system  0 02 183 Cloud detection system  0 02 184 Type of lightning detection sensor  0 02 185 Capability to detect precipitation phenomena  0 02 187 Capability to detect obscuration  0 02 188 Capability to detect obscuration  0 02 189 Capability to discriminate lightning strikes  0 04 015 Time increment (= -n minutes)  0 04 065 Short time increment (= 1 minute)  1 Delayed descriptor replication factor  1 Delayed descriptor replication factor  0 07 032 Height of sensor above water surface  0 07 033 Height of station instrument and solve true, o  0 01 004 Maximum wind gust speed  0 01 10 014 Maximum wind gust speed  0 01 10 014 Extreme counterclockwise wind direction of a			Minute <sup>(2)</sup>	Minute, 0
0 07 030		3 01 021	Latitude (high accuracy)	Degree, 5
0 07 031   Height of barometer above mean sea level   0 08 010   Surface qualifier (for temperature data)   Code table, 0   Surface station instrumentation   0 02 180   Main present weather detecting system   Code table, 0   0 02 181   Supplementary present weather sensor   Flag table, 0   0 02 182   Visibility measurement system   Code table, 0   0 02 183   Cloud detection system   Code table, 0   0 02 184   Type of lightning detection sensor   Code table, 0   0 02 179   Type of sky condition algorithm   Code table, 0   0 02 186   Capability to detect precipitation phenomena   Flag table, 0   0 02 187   Capability to detect other weather phenomena   Flag table, 0   0 02 188   Capability to detect other weather phenomena   Flag table, 0   0 02 188   Capability to discriminate lightning strikes   Flag table, 0   0 02 189   Capability to discriminate lightning strikes   Flag table, 0   0 04 015   Time increment (= -n minutes)   Minute, 0   Minute, 0   Minute, 0   Minute, 0   Delayed replication of 32 descriptors   0 01 004   Pressure   Pa, -1   Delayed descriptor replication factor (= n)   Numeric, 0   Numeric, 0   O1 004   Pressure   Pa, -1   Delayed descriptor replication factor   Numeric, 0   O1 004   Pressure   Pa, -1   Delayed descriptor replication factor   Numeric, 0   O1 1 001   Wind data   O 07 032   Height of sensor above local ground   m, 2   O 07 033   Height of sensor above water surface   m, 1   Degree true, 0   O 11 004   Maximum wind gust direction   Degree true, 0   Degree true, 0   O 11 004   Maximum wind gust direction   Degree true, 0   Degr			Longitude (high accuracy)	Degree, 5
0 08 010       Surface qualifier (for temperature data)       Code table, 0         3 01 091       Surface station instrumentation       Code table, 0         0 02 180       Main present weather detecting system       Code table, 0         0 02 181       Supplementary present weather sensor       Flag table, 0         0 02 182       Visibility measurement system       Code table, 0         0 02 183       Cloud detection system       Code table, 0         0 02 184       Type of lightning detection sensor       Code table, 0         0 02 177       Type of sky condition algorithm       Code table, 0         0 02 186       Capability to detect precipitation phenomena       Flag table, 0         0 02 187       Capability to detect other weather phenomena       Flag table, 0         0 02 188       Capability to detect obscuration       Flag table, 0         0 04 015       Time increment (= - n minutes)       Minute, 0         0 04 065       Short time increment (= 1 minute)       Minute, 0         1 32 000       Delayed replication of 32 descriptors         0 31 001       Delayed descriptor replication factor (= n)       Numeric, 0         1 02 000       Delayed replication of 2 descriptors       Numeric, 0         3 1 001       Delayed descriptor replication factor       Numeric, 0		0 07 030	Height of station ground above mean sea level	m, 1
0 08 010       Surface qualifier (for temperature data)       Code table, 0         3 01 091       Surface station instrumentation       Code table, 0         0 02 180       Main present weather detecting system       Code table, 0         0 02 181       Supplementary present weather sensor       Flag table, 0         0 02 182       Visibility measurement system       Code table, 0         0 02 183       Cloud detection system       Code table, 0         0 02 184       Type of lightning detection sensor       Code table, 0         0 02 177       Type of sky condition algorithm       Code table, 0         0 02 186       Capability to detect precipitation phenomena       Flag table, 0         0 02 187       Capability to detect other weather phenomena       Flag table, 0         0 02 188       Capability to detect obscuration       Flag table, 0         0 04 015       Time increment (= - n minutes)       Minute, 0         0 04 065       Short time increment (= 1 minute)       Minute, 0         1 32 000       Delayed replication of 32 descriptors         0 31 001       Delayed descriptor replication factor (= n)       Numeric, 0         1 02 000       Delayed replication of 2 descriptors       Numeric, 0         3 1 001       Delayed descriptor replication factor       Numeric, 0		0 07 031		m, 1
0 02 180 Main present weather detecting system 0 02 181 Supplementary present weather sensor Flag table, 0 0 02 182 Visibility measurement system Code table, 0 0 02 183 Cloud detection system Code table, 0 0 02 184 Type of lightning detection sensor Code table, 0 0 02 179 Type of sky condition algorithm Code table, 0 0 02 186 Capability to detect precipitation phenomena Flag table, 0 0 02 187 Capability to detect other weather phenomena Flag table, 0 0 02 188 Capability to detect obscuration Flag table, 0 0 02 189 Capability to discriminate lightning strikes Flag table, 0 0 04 015 Time increment (= -n minutes) Minute, 0 0 04 065 Short time increment (= 1 minute) Minute, 0  1 32 000 Delayed replication of 32 descriptors Delayed descriptor replication factor (= n) Numeric, 0 0 10 004 Pressure Pa, -1 1 02 000 Delayed replication of 2 descriptors  0 31 001 Delayed descriptor replication factor 0 0 07 032 Height of sensor above local ground m, 2 0 07 033 Height of sensor above water surface 0 11 001 Wind direction Degree true, 0 0 11 041 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 Degree true, 0	0 08 010			Code table, 0
0 02 181 Supplementary present weather sensor Flag table, 0 0 02 182 Visibility measurement system Code table, 0 0 02 183 Cloud detection system Code table, 0 0 02 184 Type of lightning detection sensor Code table, 0 0 02 179 Type of sky condition algorithm Code table, 0 0 02 186 Capability to detect precipitation phenomena Flag table, 0 0 02 187 Capability to detect other weather phenomena Flag table, 0 0 02 188 Capability to detect obscuration Flag table, 0 0 02 189 Capability to discriminate lightning strikes Flag table, 0 0 04 015 Time increment (= - n minutes) Minute, 0 0 04 065 Short time increment (= 1 minute) Minute, 0 1 32 000 Delayed replication of 32 descriptors 0 31 001 Delayed descriptor replication factor (= n) Numeric, 0 0 10 004 Pressure Pa, -1 1 02 000 Delayed replication of 2 descriptors 0 31 001 Delayed descriptor replication factor Mumeric, 0 0 07 032 Height of sensor above local ground m, 2 0 07 033 Height of sensor above water surface m, 1 0 11 001 Wind direction Degree true, 0 0 11 041 Maximum wind gust direction of a Degree true, 0 0 11 041 Maximum wind gust speed ms s <sup>-1</sup> , 1 0 11 046 Extreme counterclockwise wind direction of a Degree true, 0	3 01 091		Surface station instrumentation	
0 02 182 Visibility measurement system  0 02 183 Cloud detection system  0 02 184 Type of lightning detection sensor  0 02 179 Type of sky condition algorithm  0 02 186 Capability to detect precipitation phenomena  0 02 187 Capability to detect other weather phenomena  0 02 188 Capability to detect obscuration  0 02 189 Capability to discriminate lightning strikes  0 04 015 Flag table, 0  1 1 2 2 000 Time increment (= 1 minute)  1 2 2 000 Delayed replication of 32 descriptors  0 31 001 Delayed descriptor replication factor (= n)  1 2 2 000 Delayed replication of 2 descriptors  0 31 001 Delayed descriptor replication factor  1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		0 02 180	Main present weather detecting system	Code table, 0
0 02 182 Visibility measurement system  0 02 183 Cloud detection system  0 02 184 Type of lightning detection sensor  0 02 179 Type of sky condition algorithm  0 02 186 Capability to detect precipitation phenomena  0 02 187 Capability to detect other weather phenomena  0 02 188 Capability to detect obscuration  0 02 189 Capability to discriminate lightning strikes  0 04 015 Flag table, 0  1 1 2 2 000 Time increment (= 1 minute)  1 2 2 000 Delayed replication of 32 descriptors  0 31 001 Delayed descriptor replication factor (= n)  1 2 2 000 Delayed replication of 2 descriptors  0 31 001 Delayed descriptor replication factor  1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		0 02 181	Supplementary present weather sensor	Flag table, 0
0 02 184 Type of lightning detection sensor  0 02 179 Type of sky condition algorithm  Code table, 0  0 02 186 Capability to detect precipitation phenomena  Flag table, 0  0 02 187 Capability to detect other weather phenomena  Flag table, 0  0 02 188 Capability to detect obscuration  Flag table, 0  0 02 189 Capability to discriminate lightning strikes  Flag table, 0  0 04 015 Time increment (= - n minutes)  Minute, 0  0 04 065 Short time increment (= 1 minute)  Minute, 0  1 32 000 Delayed replication of 32 descriptors  0 31 001 Delayed descriptor replication factor (= n)  Numeric, 0  0 10 004 Pressure  Pa, -1  1 02 000 Delayed replication of 2 descriptors  0 31 001 Delayed descriptor replication factor  0 07 032 Height of sensor above local ground  m, 2  0 07 033 Height of sensor above water surface  m, 1  0 11 001 Wind direction  Degree true, 0  0 11 043 Maximum wind gust direction  Degree true, 0  0 11 041 Maximum wind gust speed  m s <sup>-1</sup> , 1  Degree true, 0  Degree true, 0  Degree true, 0		0 02 182	Visibility measurement system	Code table, 0
0 02 184 Type of lightning detection sensor  0 02 179 Type of sky condition algorithm  Code table, 0  0 02 186 Capability to detect precipitation phenomena  Flag table, 0  0 02 187 Capability to detect other weather phenomena  Flag table, 0  0 02 188 Capability to detect obscuration  Flag table, 0  0 02 189 Capability to discriminate lightning strikes  Flag table, 0  0 04 015 Time increment (= - n minutes)  Minute, 0  0 04 065 Short time increment (= 1 minute)  Minute, 0  1 32 000 Delayed replication of 32 descriptors  0 31 001 Delayed descriptor replication factor (= n)  Numeric, 0  0 10 004 Pressure  Pa, -1  1 02 000 Delayed replication of 2 descriptors  0 31 001 Delayed descriptor replication factor  0 07 032 Height of sensor above local ground  m, 2  0 07 033 Height of sensor above water surface  m, 1  0 11 001 Wind direction  Degree true, 0  0 11 043 Maximum wind gust direction  Degree true, 0  0 11 041 Maximum wind gust speed  m s <sup>-1</sup> , 1  Degree true, 0  Degree true, 0  Degree true, 0		0 02 183	Cloud detection system	Code table, 0
0 02 186 Capability to detect precipitation phenomena 0 02 187 Capability to detect other weather phenomena Flag table, 0 0 02 188 Capability to detect obscuration Flag table, 0 0 02 189 Capability to discriminate lightning strikes Flag table, 0 0 04 015 Time increment (= -n minutes) Minute, 0 0 04 065 Short time increment (= 1 minute) Minute, 0  1 32 000 Delayed replication of 32 descriptors 0 31 001 Delayed descriptor replication factor (= n) Numeric, 0 0 10 004 Pressure Pa, -1 1 02 000 Delayed replication of 2 descriptors 0 31 001 Delayed descriptor replication factor Numeric, 0 0 10 004 Height of sensor above local ground m, 2 0 07 032 Height of sensor above water surface 0 11 001 Wind direction Degree true, 0 0 11 002 Wind speed m s <sup>-1</sup> , 1 0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 Degree true, 0		0 02 184		Code table, 0
0 02 187 Capability to detect other weather phenomena 0 02 188 Capability to detect obscuration 0 02 189 Capability to discriminate lightning strikes Flag table, 0 Time increment (= - n minutes) Minute, 0  0 04 015 Short time increment (= 1 minute) Minute, 0  1 32 000 Delayed replication of 32 descriptors Delayed descriptor replication factor (= n) Numeric, 0  1 10 004 Pressure Pa, -1  1 02 000 Delayed descriptor replication factor Numeric, 0  3 1 001 Delayed descriptor replication factor Minute, 0  0 10 004 Pressure Pa, -1  1 02 000 Delayed descriptor replication factor Numeric, 0  3 1 001 Delayed descriptor replication factor Numeric, 0  0 10 07 032 Height of sensor above local ground m, 2 0 07 033 Height of sensor above water surface m, 1 0 11 001 Wind direction Degree true, 0 0 11 002 Wind speed ms <sup>-1</sup> , 1 0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed ms <sup>-1</sup> , 1 Degree true, 0		0 02 179	Type of sky condition algorithm	Code table, 0
0 02 188 Capability to detect obscuration 0 02 189 Capability to discriminate lightning strikes Flag table, 0 Time increment (= -n minutes) Minute, 0 O 04 065 Short time increment (= 1 minute) Minute, 0  1 32 000 Delayed replication of 32 descriptors Delayed descriptor replication factor (= n) Numeric, 0 O 10 004 Pressure Pa, -1  1 02 000 Delayed replication of 2 descriptors Delayed descriptor replication factor Minute, 0  Numeric, 0  Value of the part of th		0 02 186	Capability to detect precipitation phenomena	Flag table, 0
0 02 188 Capability to detect obscuration 0 02 189 Capability to discriminate lightning strikes Flag table, 0  0 04 015 Time increment (= -n minutes) Minute, 0  0 04 065 Short time increment (= 1 minute)  1 32 000 Delayed replication of 32 descriptors  0 31 001 Delayed descriptor replication factor (= n)  0 10 004 Pressure Pa, -1  1 02 000 Delayed replication of 2 descriptors  0 31 001 Delayed descriptor replication factor  1 02 000 Delayed descriptor replication factor Mumeric, 0  1 0 07 032 Height of sensor above local ground Minute, 0  0 07 033 Height of sensor above water surface Minute, 0  1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		0 02 187	Capability to detect other weather phenomena	Flag table, 0
Time increment (= - n minutes)  Short time increment (= 1 minute)  Minute, 0  Delayed replication of 32 descriptors  Delayed descriptor replication factor (= n)  Delayed replication of 2 descriptors  Delayed descriptor replication factor  Numeric, 0  Minute, 0  Numeric, 0  Numeric, 0  Pressure  Delayed replication of 2 descriptors  Delayed descriptor replication factor  Numeric, 0		0 02 188	Capability to detect obscuration	
0 04 065Short time increment ( = 1 minute)Minute, 01 32 000Delayed replication of 32 descriptors0 31 001Delayed descriptor replication factor (= n)Numeric, 00 10 004PressurePa, -11 02 000Delayed replication of 2 descriptors0 31 001Delayed descriptor replication factorNumeric, 03 02 070Wind data0 07 032Height of sensor above local groundm, 20 07 033Height of sensor above water surfacem, 10 11 001Wind directionDegree true, 00 11 002Wind speedm s-1, 10 11 043Maximum wind gust directionDegree true, 00 11 041Maximum wind gust speedm s-1, 10 11 016Extreme counterclockwise wind direction of aDegree true, 0		0 02 189	Capability to discriminate lightning strikes	Flag table, 0
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Delayed descriptor replication factor (= n)  Delayed descriptor replication factor (= n)  Pressure  Delayed replication of 2 descriptors  Delayed descriptor replication factor  Numeric, 0  Wind data  O 07 032 Height of sensor above local ground  Height of sensor above water surface  O 11 001 Wind direction  Degree true, 0  O 11 002 Wind speed  Maximum wind gust direction  Degree true, 0  O 11 041 Maximum wind gust speed  Mumeric, 0  Numeric, 0	0 04 065		Short time increment ( = 1 minute)	Minute, 0
Delayed descriptor replication factor (= n)  Delayed descriptor replication factor (= n)  Delayed replication of 2 descriptors  Delayed descriptor replication factor  Mumeric, 0  Delayed descriptor replication factor  Numeric, 0  Wind data  0 07 032 Height of sensor above local ground m, 2  0 07 033 Height of sensor above water surface m, 1  0 11 001 Wind direction Degree true, 0  0 11 002 Wind speed ms <sup>-1</sup> , 1  0 11 043 Maximum wind gust direction Degree true, 0  0 11 041 Maximum wind gust speed ms <sup>-1</sup> , 1  Degree true, 0	1 32 000		Delayed replication of 32 descriptors	
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Delayed descriptor replication factorNumeric, 03 02 070Wind data0 07 032Height of sensor above local groundm, 20 07 033Height of sensor above water surfacem, 10 11 001Wind directionDegree true, 00 11 002Wind speedm s <sup>-1</sup> , 10 11 043Maximum wind gust directionDegree true, 00 11 041Maximum wind gust speedm s <sup>-1</sup> , 10 11 016Extreme counterclockwise wind direction of aDegree true, 0	1 02 000		Delayed replication of 2 descriptors	·
0 07 032 Height of sensor above local ground m, 2 0 07 033 Height of sensor above water surface m, 1 0 11 001 Wind direction Degree true, 0 0 11 002 Wind speed m s <sup>-1</sup> , 1 0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 0 11 016 Extreme counterclockwise wind direction of a Degree true, 0	0 31 001			Numeric, 0
0 07 033 Height of sensor above water surface m, 1 0 11 001 Wind direction Degree true, 0 0 11 002 Wind speed m s <sup>-1</sup> , 1 0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 0 11 016 Extreme counterclockwise wind direction of a Degree true, 0	3 02 070		Wind data	
0 07 033 Height of sensor above water surface m, 1 0 11 001 Wind direction Degree true, 0 0 11 002 Wind speed m s <sup>-1</sup> , 1 0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 0 11 016 Extreme counterclockwise wind direction of a Degree true, 0		0 07 032	Height of sensor above local ground	m, 2
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0 11 002 Wind speed m s <sup>-1</sup> , 1 0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 0 11 016 Extreme counterclockwise wind direction of a Degree true, 0		0 11 001	Wind direction	
0 11 043 Maximum wind gust direction Degree true, 0 0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 0 11 016 Extreme counterclockwise wind direction of a Degree true, 0		0 11 002	Wind speed	
0 11 041 Maximum wind gust speed m s <sup>-1</sup> , 1 0 11 016 Extreme counterclockwise wind direction of a Degree true, 0			Maximum wind gust direction	Degree true, 0
0 11 016 Extreme counterclockwise wind direction of a Degree true, 0		0 11 041	Maximum wind gust speed	m s <sup>-1</sup> , 1
variable wind		0 11 016	Extreme counterclockwise wind direction of a	
			variable wind	

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0 11 017   Extreme clockwise wind direction of a variable wind   Degree true, 0		0 11 017	Extreme electrics wind direction of a variable wind	Dograo truo O
0 07 032	2 02 072	0 11 017		Degree true, 0
0 07 033	3 02 072	0.07.022		m 2
0 12 101   Temperature/Air-temperature (scale 2)				
0 12 103			U U	
0 13 003				
103 000   Delayed replication of 3 descriptors   Numeric, 0				
0 31 001         Delayed descriptor replication factor         Numeric, 0           0 07 032         Height of sensor above local ground (**)         m, 2           0 08 010         Surface qualifier         Code table, 0           0 12 120         Ground temperature         K, 2           0 07 032         Height of sensor above local ground (set to missing to cancel the previous value)         m, 2           0 80 10         Surface qualifier (set to missing to cancel the previous value)         Code table, 0           1 03 000         Delayed replication of 3 descriptors         Numeric, 0           1 01 005         Replicate 1 descriptor five times         Numeric, 0           3 07 063         0 07 061         Depth below land surface         m, 2           0 07 063         Depth below land surface         m, 2           0 07 063         Depth below land surface         m, 2           0 07 063         Depth below land surface         m, 2           0 07 081         Depth below land surface         m, 2           0 10 000         Delayed replication of 1 descriptor         Numeric, 0           3 02 069         Visibility data         m, 2           0 07 033         Height of sensor above local ground         m, 2           0 07 034         Height of sensor above local ground	4.00.000	0 13 003		%, U
0 07 032				N
0 8 010         Surface qualifier         Code table, 0           0 12 120         Ground temperature         K, 2           0 07 032         Height of sensor above local ground (set to missing to cancel the previous value)         m, 2           0 08 010         Surface qualifier (set to missing to cancel the previous value)         Code table, 0           1 03 000         Delayed replication of 3 descriptors         Numeric, 0           0 31 000         Short delayed descriptor replication factor         Numeric, 0           1 01 005         Replicate 1 descriptor five times         m, 2           0 07 061         Depth below land surface         m, 2           0 07 061         Depth below land surface         m, 2           0 07 061         Depth below land surface         m, 2           0 10 1000         Delayed replication of 1 descriptor         m, 2           0 10 000         Short delayed descriptor replication factor         Numeric, 0           3 1000         Short delayed descriptor replication factor         Numeric, 0           3 02 069         Visibility data         m, 1           0 07 033         Height of sensor above water surface         m, 1           0 07 034         Height of sensor above water surface         m, 1           0 07 035         Height of sensor above wat				· ·
0 12 120         Ground temperature         K, 2           0 07 032         Height of sensor above local ground (set to missing to cancel the previous value)         m, 2           0 08 010         Surface qualifier (set to missing to cancel the previous value)         Code table, 0           1 03 000         Delayed replication of 3 descriptors         Numeric, 0           0 1 000         Short delayed descriptor replication factor         Numeric, 0           1 01 005         Replicate 1 descriptor five times         m, 2           3 07 063         0 07 061         Depth below land surface         m, 2           0 07 061         Depth below land surface         m, 2           0 07 061         Depth below land surface         m, 2           (set to missing to cancel the previous value)         m, 2           0 07 061         Delayed replication of 1 descriptor         Numeric, 0           0 1 000         Delayed replication of 1 descriptor         Numeric, 0           0 31 000         Short delayed descriptor replication factor         Numeric, 0           0 20 099         Visibility data         m, 1           0 0 7 032         Height of sensor above local ground         m, 2           0 0 7 034         Height of sensor above local ground         m, 1           0 0 7 035         Height o				
Name				
Set to missing to cancel the previous value   Code table, 0 (set to missing to cancel the previous value)				•
O 8 010	0 07 032			m, 2
Set to missing to cancel the previous value   1 03 000   Delayed replication of 3 descriptors   Numeric, 0   1 01 005   Replicate 1 descriptor five times   3 07 063   0 07 061   Depth below land surface   m, 2   K, 2   0 07 061   Depth below land surface   m, 2   K, 2   0 07 061   Depth below land surface   m, 2   K, 2   0 07 061   Depth below land surface   m, 2   K, 2   0 07 061   Depth below land surface   m, 2   K, 2   0 07 061   Depth below land surface (set to missing to cancel the previous value)   0 10 00   Delayed replication of 1 descriptor   Numeric, 0   31 000   Short delayed descriptor replication factor   Numeric, 0   30 20 69   Visibility data   Numeric, 0   Numeric, 0   0 07 032   Height of sensor above local ground   m, 2   0 07 032   Height of sensor above water surface   m, 1   0 07 032   Height of sensor above local ground   m, 2   0 07 032   Height of sensor above water surface   m, 1   0 07 032   Height of sensor above water surface (set to missing to cancel the previous value)   Numeric, 0   0 07 033   Height of sensor above water surface (set to missing to cancel the previous value)   Numeric, 0   0 07 031   OD   Delayed replication of 1 descriptor   Numeric, 0   0 07 031   OD   Delayed replication of 1 descriptor   Numeric, 0   0 07 07 07   OD   Delayed replication of 1 descriptor   Numeric, 0   0 07 07 07   OD   OD   OD   OD   OD   OD   OD   O	0.00.040			
0 30 000         Delayed replication of 3 descriptors         Numeric, 0           0 31 000         Short delayed descriptor replication factor         Numeric, 0           0 10 005         Replicate 1 descriptor five times         m, 2           3 07 063         0 07 061         Depth below land surface         m, 2           0 07 061         Depth below land surface         m, 2           (set to missing to cancel the previous value)         m, 2           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           0 31 000         Short delayed descriptor replication factor         Numeric, 0           0 31 000         Short delayed descriptor replication factor         Numeric, 0           0 07 032         Height of sensor above local ground         m, 2           0 07 033         Height of sensor above water surface         m, 1           0 07 032         Height of sensor above local ground         m, -1           0 07 033         Height of sensor above water surface         m, 1           0 07 034         Height of sensor above water surface         m, 1           0 07 035         Height of sensor above water surface         m, 1           0 07 036         Height of sensor above water surface         m, 1           0 07 037         Height of sensor above water s	0 08 010			Code table, 0
0 31 000         Short delayed descriptor replication factor         Numeric, 0           1 01 005         Replicate 1 descriptor five times         m, 2           3 07 063         0 07 061         Depth below land surface         m, 2           0 07 061         Depth below land surface (set to missing to cancel the previous value)         m, 2           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 1 000         Short delayed descriptor replication factor         Numeric, 0           3 02 069         Visibility data         m, 2           0 0 7 032         Height of sensor above local ground         m, 2           0 0 3 3 041         Attribute of following value         Code table, 0           0 0 7 032         Height of sensor above water surface         m, 1           0 0 7 033         Height of sensor above local ground         m, 2           0 0 7 033         Height of sensor above water surface         m, 1           0 1 0 00         Short delayed descriptor previous value)         m, 1           0 1 0 00         Delayed replication of 1 descriptor         Numeric, 0           0 31 000         Short delayed descriptor replication factor         Numeric, 0           0 20 073         Cloud data         Cloud data         Code table, 0	4 00 000			
101 005			Delayed replication of 3 descriptors	
3 07 063				Numeric, 0
0 12 130		0.07.55		
0 07 061         Depth below land surface (set to missing to cancel the previous value)         m, 2           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 1 000         Short delayed descriptor replication factor         Numeric, 0           3 02 069         Visibility data         m, 2           0 07 032         Height of sensor above local ground         m, 1           0 33 041         Attribute of following value         Code table, 0           0 07 032         Height of sensor above water surface         m, 1           0 07 033         Height of sensor above water surface         m, 1           0 07 033         Height of sensor above water surface         m, 1           0 1 000         Delayed replication of 1 descriptor         m, 1           0 31 000         Short delayed descriptor replication factor         Numeric, 0           0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	3 07 063			
(set to missing to cancel the previous value)  Delayed replication of 1 descriptor  Short delayed descriptor replication factor  Visibility data  0 07 032 Height of sensor above local ground m, 2  0 30 20 69 Height of sensor above water surface m, 1  0 33 041 Attribute of following value Code table, 0  0 20 001 Horizontal visibility m, -1  Height of sensor above local ground m, 2  Height of sensor above local ground (set to missing to cancel the previous value)  0 07 032 Height of sensor above local ground (set to missing to cancel the previous value)  1 01 000 Delayed replication of 1 descriptor  0 31 000 Short delayed descriptor replication factor Numeric, 0  3 02 073 Cloud data  0 20 010 Cloud cover (total) %, 0  1 05 004 Replicate 5 descriptors four times  0 08 002 Vertical significance Code table, 0  0 20 011 Cloud amount Code table, 0  0 20 012 Cloud type Code table, 0  0 20 013 Height of base of cloud m, -1  1 01 000 Delayed replication of 1 descriptor  0 31 000 Short delayed descriptor replication factor Numeric, 0  Figure Code table, 0  0 20 012 Cloud ytype Code table, 0  0 20 013 Height of base of cloud m, -1  1 01 000 Delayed replication of 1 descriptor  3 10 20 076 Precipitation, obscuration and other phenomena  0 20 020 Character of precipitation  Flag table, 0  0 20 020 Other weather phenomena  Flag table, 0  1 0 20 025 Obscuration  Flag table, 0  Code table, 0  Flag table, 0  Flag table, 0  Flag table, 0		0 12 130		K, 2
1 01 000	0 07 061		<u> </u>	m, 2
0 31 000         Short delayed descriptor replication factor         Numeric, 0           3 02 069         Visibility data         m, 2           0 07 032         Height of sensor above water surface         m, 1           0 33 041         Attribute of following value         Code table, 0           0 07 032         Height of sensor above local ground (set to missing to cancel the previous value)         m, −1           0 07 033         Height of sensor above water surface (set to missing to cancel the previous value)         m, 1           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 1 000         Short delayed descriptor replication factor         Numeric, 0           3 02 073         Cloud cover (total)         %, 0           1 05 004         Replicate 5 descriptors four times           0 08 002         Vertical significance         Code table, 0           0 20 011         Cloud amount         Code table, 0           0 20 012         Cloud type         Code table, 0           0 20 013         Height of base of cloud         m, −1           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 02 076         Precipitation, obscuration and other phenomena         Numeric, 0           3 02 076         Precipitation, obscuration a				
3 02 069				
0 07 032				Numeric, 0
0 07 033   Height of sensor above water surface   m, 1	3 02 069			
0 33 041 Attribute of following value m, -1 0 07 032 Height of sensor above local ground (set to missing to cancel the previous value)  0 07 033 Height of sensor above water surface (set to missing to cancel the previous value)  1 01 000 Delayed replication of 1 descriptor  0 31 000 Short delayed descriptor replication factor Numeric, 0  3 02 073 Cloud data  0 20 010 Cloud cover (total) %, 0  1 05 004 Replicate 5 descriptors four times  0 08 002 Vertical significance Code table, 0 0 20 011 Cloud amount Code table, 0 0 20 012 Cloud type Code table, 0 0 20 013 Height of base of cloud m, -1  1 01 000 Delayed replication of 1 descriptor  0 31 000 Short delayed descriptor replication factor Short delayed descriptor Four times  0 08 002 Vertical significance Code table, 0 0 20 012 Cloud type Code table, 0 0 20 013 Height of base of cloud m, -1  1 01 000 Delayed replication of 1 descriptor  0 31 000 Short delayed descriptor replication factor Numeric, 0  3 02 076 Precipitation, obscuration and other phenomena  0 20 021 Type of precipitation Flag table, 0 0 20 022 Character of precipitation Code table, 0 0 20 023 Other weather phenomena Flag table, 0 0 20 024 Intensity of phenomena Flag table, 0 0 20 025 Obscuration Flag table, 0 Flag table, 0 0 20 026 Character of obscuration Flag table, 0				
0 20 001   Horizontal visibility   m, -1				
Height of sensor above local ground (set to missing to cancel the previous value)  Height of sensor above water surface (set to missing to cancel the previous value)  Delayed replication of 1 descriptor  Short delayed descriptor replication factor  Numeric, 0  Cloud data  O 20 010 Cloud cover (total)  Replicate 5 descriptors four times  O 80 002 Vertical significance  O 20 011 Cloud amount  Code table, 0  O 20 012 Cloud type  Code table, 0  O 20 013 Height of base of cloud  O 20 013 Height of base of cloud  Delayed replication of 1 descriptor  Short delayed descriptor replication factor  Numeric, 0  Code table, 0  O 20 012 Cloud type  Code table, 0  O 20 013 Height of base of cloud  Delayed replication of 1 descriptor  Short delayed descriptor replication factor  Numeric, 0  Precipitation, obscuration and other phenomena  O 20 021 Type of precipitation  O 20 022 Character of precipitation  O 20 023 Other weather phenomena  Flag table, 0  O 20 020 Other weather phenomena  Flag table, 0  O 20 025 Obscuration  Flag table, 0  Code table, 0  Flag table, 0  Flag table, 0  Flag table, 0  Code table, 0  Flag table, 0  Code table, 0				
(set to missing to cancel the previous value)  0 07 033		0 20 001		
Height of sensor above water surface (set to missing to cancel the previous value)	0 07 032			m, 2
(set to missing to cancel the previous value)  Delayed replication of 1 descriptor  Short delayed descriptor replication factor  Cloud data  Cloud cover (total)  Replicate 5 descriptors four times  O 20 011 Cloud amount  Code table, 0  O 20 012 Cloud type  Code table, 0  O 33 041 Attribute of following value  O 20 013 Height of base of cloud  Delayed replication of 1 descriptor  Short delayed descriptor replication factor  Numeric, 0  O 20 013 Precipitation, obscuration and other phenomena  O 20 022 Character of precipitation  O 20 023 Other weather phenomena  Flag table, 0  O 20 025 Obscuration  Flag table, 0  Code table, 0  Code table, 0  Flag table, 0  Code table, 0  Code table, 0  Code table, 0  Flag table, 0  Code table, 0  Code table, 0  Flag table, 0  Code table, 0				
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0 31 000         Short delayed descriptor replication factor         Numeric, 0           3 02 073         Cloud data         %, 0           0 20 010         Cloud cover (total)         %, 0           1 05 004         Replicate 5 descriptors four times         Code table, 0           0 20 011         Cloud amount         Code table, 0           0 20 012         Cloud type         Code table, 0           0 20 012         Cloud type         Code table, 0           0 33 041         Attribute of following value         Code table, 0           0 20 013         Height of base of cloud         m, -1           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 1 000         Short delayed descriptor replication factor         Numeric, 0           3 02 076         Precipitation, obscuration and other phenomena         Flag table, 0           0 20 021         Type of precipitation         Flag table, 0           0 20 022         Character of precipitation <sup>(3)</sup> Minute, 0           0 20 023         Other weather phenomena         Flag table, 0           0 20 024         Intensity of phenomena         Code table, 0           0 20 025         Obscuration         Flag table, 0           0 20 026         Character of obscu	4.04.000			
3 02 073         Cloud data           0 20 010         Cloud cover (total)         %, 0           1 05 004         Replicate 5 descriptors four times           0 08 002         Vertical significance         Code table, 0           0 20 011         Cloud amount         Code table, 0           0 20 012         Cloud type         Code table, 0           0 33 041         Attribute of following value         Code table, 0           0 20 013         Height of base of cloud         m, -1           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 1 000         Short delayed descriptor replication factor         Numeric, 0           3 02 076         Precipitation, obscuration and other phenomena         Flag table, 0           0 20 021         Type of precipitation         Code table, 0           0 20 022         Character of precipitation         Code table, 0           0 20 023         Other weather phenomena         Flag table, 0           0 20 024         Intensity of phenomena         Code table, 0           0 20 025         Obscuration         Flag table, 0           0 20 026         Character of obscuration         Code table, 0				
0 20 010         Cloud cover (total)         %, 0           1 05 004         Replicate 5 descriptors four times         Code table, 0           0 08 002         Vertical significance         Code table, 0           0 20 011         Cloud amount         Code table, 0           0 20 012         Cloud type         Code table, 0           0 33 041         Attribute of following value         Code table, 0           0 20 013         Height of base of cloud         m, -1           1 01 000         Delayed replication of 1 descriptor         Numeric, 0           3 1 000         Short delayed descriptor replication factor         Numeric, 0           3 02 076         Precipitation, obscuration and other phenomena         Flag table, 0           0 20 021         Type of precipitation         Code table, 0           0 20 022         Character of precipitation of precipitation of precipitation (3)         Minute, 0           0 20 023         Other weather phenomena         Flag table, 0           0 20 024         Intensity of phenomena         Code table, 0           0 20 025         Obscuration         Flag table, 0           0 20 026         Character of obscuration         Code table, 0				Numeric, 0
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1 02 000 Delayed replication of 2 descriptors				
, , , , , , , , , , , , , , , , , , , ,			Character of obscuration	

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0.04.000			TN : 0
0 31 000		Short delayed descriptor replication factor	Numeric, 0
0 13 155		Intensity of precipitation	kgm <sup>-2</sup> s <sup>-1</sup> , 4
0 13 058		Size of precipitation element	m, 4
4.00.000		(end of the replicated sequence)	
1 02 000		Delayed replication of 2 descriptors	N
0 31 000		Short delayed descriptor replication factor	Numeric, 0
0 20 031		Ice deposit (thickness)	m, 2
0 20 032		Rate of ice accretion	Code table, 0
1 01 000		Delayed replication of 1 descriptor	Numaria O
0 31 000		Short delayed descriptor replication factor	Numeric, 0
3 02 078	0.02.176	State of ground and snow depth measurement	Codo tabla 0
	0 02 176 0 20 062	Method of state of ground measurement	Code table, 0
	0 02 177	State of ground (with or without snow)	Code table, 0
	0 13 013	Method of snow depth measurement	Code table, 0
1 02 000	0 13 013	Total snow depth	m, 2
		Delayed replication of 2 descriptors	Numaria 0
0 31 000 <b>3 02 079</b>		Short delayed descriptor replication factor	Numeric, 0
3 02 079	0 07 032	Precipitation measurement Height of sensor above local ground	m, 2
	0 07 032		Code table, 0
	0 02 173	Method of precipitation measurement	Code table, 0
	0 02 176	Method of liquid water content measurement of precipitation	Code lable, 0
	0 04 025	Time period (= - n minutes)	Minute, 0
	0 13 011	Total precipitation / total water equivalent of snow	kg m <sup>-2</sup> , 1
0 07 032	0 13 011	Height of sensor above local ground	m, 2
0 07 032		(set to missing to cancel the previous value)	111, 2
1 01 000		Delayed replication of 1 descriptor	
0 31 000		Short delayed descriptor replication factor	Numeric, 0
3 02 080		Evaporation measurement	ivallicite, o
3 02 000	0 02 185	Method of evaporation measurement	Code table, 0
	0 04 025	Time period or displacement ( = - n minutes)	Minute, 0
	0 13 033	Evaporation /evapotranspiration	kg m <sup>-2</sup> , 1
1 01 000	0 10 000	Delayed replication of 1 descriptor	Ng III , I
0 31 000		Short delayed descriptor replication factor	Numeric, 0
3 02 081		Total sunshine data	Trainiono, o
0 02 00 :	0 04 025	Time period (= - n minutes)	Minute, 0
	0 14 031	Total sunshine	Minute, 0
1 01 000		Delayed replication of 1 descriptor	
0 31 000		Short delayed descriptor replication factor	Numeric, 0
3 02 082		Radiation data	,
	0 04 025	Time period (= - n minutes)	Minute, 0
	0 14 002	Long-wave radiation, integrated over period	J m <sup>-2</sup> , -3
		specified	
	0 14 004	Short-wave radiation, integrated over period	J m <sup>-2</sup> , -3
		specified	
	0 14 016	Net radiation, integrated over period specified	J m <sup>-2</sup> , -4 J m <sup>-2</sup> , -2
	0 14 028	Global solar radiation (high accuracy),	J m <sup>-2</sup> , -2
		integrated over period specified	
	0 14 029	Diffuse solar radiation (high accuracy),	J m <sup>-2</sup> , -2
		integrated over period specified	
	0 14 030	Direct solar radiation (high accuracy),	J m <sup>-2</sup> , -2
		integrated over period specified	
1 02 000		Delayed replication of 2 descriptors	
0 31 000		Short delayed descriptor replication factor	Numeric, 0
0 04 025		Time period (= - n minutes)	Minute

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0 13 059		Number of flashes	Numeric
1 01 000		Delayed replication of 1 descriptor	
0 31 000		Short delayed descriptor replication factor	Numeric, 0
3 02 083		First order statistics of P, W, T, U data	
	0 04 025	Time period (= - n minutes)	Minute, 0
	0 08 023	First order statistics	Code table, 0
		(= 9; best estimate of standard deviation) (4)	
	0 10 004	Pressure	Pa, -1
	0 11 001	Wind direction	Degree true, 0
	0 11 002	Wind speed	m s <sup>-1</sup> , 1
	0 12 101	Temperature/dry-bulb temperature (scale 2)	K, 2
	0 13 003	Relative humidity	%, 0
	0 08 023	First order statistics (= missing value)	Code table, 0
0 33 005		Quality information (AWS data)	Flag table, 0
0 33 006		Internal measurement status information (AWS)	Code table, 0

#### Notes:

- 1) 0 01 101 (WMO Member State identifier) and 0 01 102 (National AWS number) shall be used to identify a station within the national numbering system that is completely independent of the WMO international numbering system. The WMO international identification 0 01 001 (WMO block number) and 0 01 002 (WMO station number) shall be reported if available for the particular station.
- 2) The time identification refers to the end of the n-minute period.
- 3) Duration of precipitation (in minutes) represents number of minutes in which any precipitation was registered.
- 4) Best estimate of standard deviation is counted out of a set of samples (signal measurements) recorded within the period specified; it should be reported as a missing value, if the measurements of the relevant element are not available from a part of the period specified by 0 04 025.
- 5) If reporting nominal values is required, the template shall be supplemented with 3 07 093.
- 6) The height above local ground 0 07 032 referring to ground temperature shall be considered as a variable. After a snowfall, the sensor is placed at the top of the snow layer and the changed value of 0 07 032 shall indicate this procedure (the depth of the snow is reported in 0 13 013).

# Advances in AWS Technology Review progress and advances in AWS technologies - Develop guidance to deal with integration of third party AWS networks

Submitted by Dr Jane Warne (Australia)

J.Warne@bom.gov.au

### DECISION PROCESS FOR THE INTEGRATION OF EXTERNAL DATA SOURCES INTO NATIONAL METEOROLOGICAL ORGANISATIONS

A common problem which impacts many modern meteorological organisations is how to effectively use and integrate data from external sources. Historically the decisions to use this data may have been made on an *ad hoc* basis and not necessarily considered the operational cost of using and maintaining such sources of data. It is sometimes assumed that data provided at nominally no cost to meteorological organisation is free, however, this is seldom case. There are costs associated with ingest and potential archival of the data. If the data is critical to operations then monitoring of both the quality and the availability of the data becomes critical. Issues around intellectual property rights and obligations, relationship management and contract management all create an economic impost on the organisation. As a consequence, "free data." is seldom free. It is therefore important to be able to determine the value of the data source and hence whether investment in its management is justified.

To make an informed decision regarding use or investment in external data there are several areas that need to be considered. They can be summarised as:-

- Value What does this data or arrangement deliver to the organisation?
- Metadata Do you know enough about the data to make effective use of it?
- Intellectual property Can you use the data in the way we want?
- Implementation Can you access and manage the data?
- Agreement Do you have the mutual ability to manage the relationship in the future?

A decision process to address these five issues is given in Figure 1. This provides a logical flow decision-making which progresses through each of the above areas. If for any reason the source fails to meet the needs of the process, then no more energy and resource need be invested. Having this process should therefore limit negative economic, risk and resource impacts of ingesting external data. It is important to note this is a decision process not an implementation process.

#### Value

Ingestion of data, its management, archival and dissemination, are all costly process unless data is adding value to an operational research outcome. There is little point in making the investment associated with managing that data if we're not deriving value. With this in mind the following decision process commences with an assessment of value in three different areas; relationship, network contribution and quality of the data.

Questions that could be asked at this stage are:-

- Is maintaining a healthy relationship with this provider critical to the broader goals of the organisation?
- Why do you want particular data or information?
- What do you need to know to judge the value of the information?
- How do you know that the information is adding value i.e. that is what is the KPI (Key Performance Index)?
- Spatially is the data filling a gap in a network or providing redundancy?
- What is the quality of the data?
- Are there risks or costs in having too much data?

Fundamentally it needs to be determined how this data source delivers value to the organisation.

Is the relationship with the supplier sufficiently important that despite minor issues with the data it is worth engaging for the relationship alone? An example of this would be the acceptance of AWS data that is over sampling an area or which is of lower quality to ensure delivery of critical remote sensing data to another program. In this situation concerns about the quality (which may be managed in a tier structure) are secondary to shoring up the relationship. This is fundamentally the most subjective measure of value, and will need to be considered on site by site and supplier basis.

A second consideration is the spatial contribution the data/information makes to the organisation. This is often a balance between the quality and usefulness aspects of the data and is driven by end user. Critical to the ultimate decision is a detailed understanding of the user needs (potentially via a Rolling Review of Requirements process).

Another critical input to this decision is an integrated a network design. Network designs need to be a balance of various user needs, an understanding of meteorological and environmental threats, and ideally an understanding of national infrastructure, societal and environmental priorities. Integrated GIS tools that draw on National economic and societal data along with value estimates from meteorological model outputs, such as adjoint based sensitivity and ensemble analysis, are useful tools in determining the value of individual data sources.

The next stage in assessing the value of new data sources is its quality and utility. Criteria such as the frequency of data delivery, reliability of delivery, longevity and the quality of information supplied should be assessed. If the data does not satisfy the requirements of particular users then there is no sense in its collection, archival or quality control unless the relationship is paramount.

Having considered and determined there is some merit or value in the delivered data. The final stage of value assessment is to make a preliminary determination of the tier the data belongs to. This will assist with related decisions on data requirements, the nature of an agreement and intellectual property rights. Clearly this step assumes implementation of a "Tiered network" that incorporates and rates sources of data based on the quality and all usefulness. Such a system will allow the organisation to better manage data of varied quality, but is not essential to the operation of a decision process.

There are, five key tools needed to aid in this stage of the decision process (Fig. 1a).

A set of principles or guidelines for deciding value of relationships

<sup>&</sup>lt;sup>2</sup> Note from this point forward you should assume the use of a tier system within the operation of networks. In general, this does not negate any of the stages of the decision process, however minor modifications may be needed if implementing in a non-tiered network.

- A list or policy regarding critical relationships
- User requirements that articulate the quality, frequency, reliability and the spatial distribution of data needed.
- A network design which reflects the user's spatial requirements for a particular data type.
- Quality standards and criteria for the data for tiers, if implemented.

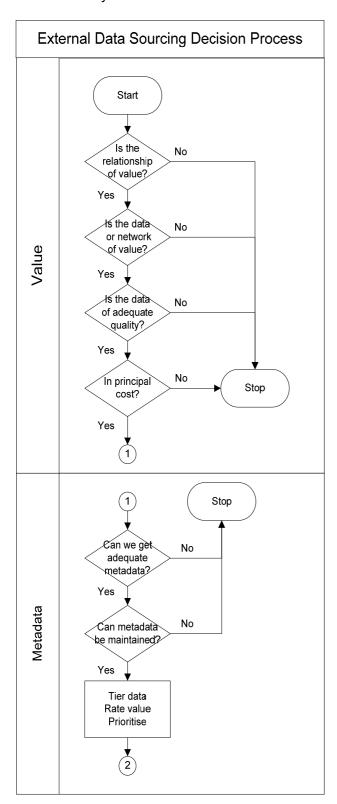


Figure 1a. External data is sourcing decision process flow diagram – Determining Value

#### Metadata

The second stage in this process is to assess the metadata needs. What metadata is essential to make the data useful? How do we gather metadata? What resources are needed to maintain the data? (Fig. 1a).

Metadata falls into several categories:-

- ownership and management (e.g. infrastructure owner, property owner, operating contact, leasing arrangements, length of tenure);
- geographic (e.g. Latitude, longitude, elevation);
- measurement infrastructure (e.g. sensors, age of infrastructure);
- siting (e.g. photographs, skyline surveys, plans, land type);
- communications and reporting (e.g. frequency of reporting, format, the method of reporting);
- algorithms and software (e.g. sampling methods, processing);
- standards and calibration (e.g., traceability, uncertainty estimates, compliance certification, maintenance schedule);
- quality control (e.g. post-processing, flags);
  - Date, record coverage period;
  - Archive information; (Electronic/paper) access to historical data.

The quantity, quality and currency of metadata will govern the usefulness of the data and hence the tier to which the data will contribute. As a result if an adequate level of metadata is not available there may be no point in continuing to consider ingesting the external data.

A further consideration is whether the metadata can be maintained on a regular basis. To minimise costs and maximise value this should be a task undertaken by the supplier of the data. In most data formats a minimum metadata of time and location or site number are provided which links the data to the more detailed site, quality and ownership metadata. To update the metadata related to a site there needs to be a separate process which provides details on the sensors used calibrations and maintenance etc. Model transfer formats such as BUFR and XML tend to carry more detailed metadata on a message by message basis. Meteorological Service Canada are taking this approach to what might be considered "routine" metadata. Such methods cater for some, not all metadata requirements. As a consequence, organisations need to consider developing simple access paths for external organisations to maintain more detailed metadata e.g. via Web interface.

To progress this aspect of process will require:-

- Metadata for each tier level, and an assessment of the risks associated with not having metadata.
- A mechanism for external agencies to submit and update metadata records.

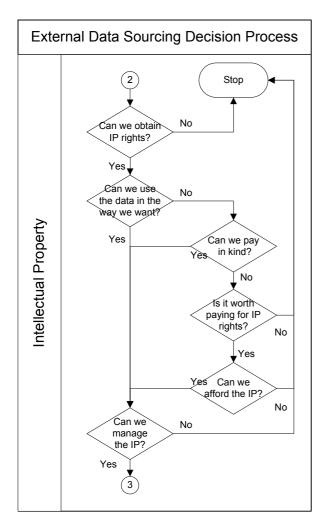


Figure 1b. External data is sourcing decision process flow diagram – Intellectual Property

#### Intellectual property (IP)

The next issue to be addressed is that of IP rights. Reaching agreement on custodianship of data is important. There needs to be an understanding of how the data can be used so that incumbent limitations can be efficiently managed. Some providers of data may wish to place restrictions on redistribution and/or internal use of the data. Where possible these should be avoided as they increase significantly the cost and risk associated with the use of the data. For example, without adequate controls over the release of data it is very easy for individual members of the organisation to unwittingly redistribute data which has limitations on it. Managing those controls can also add significantly to the overhead costs.

In some rare cases the value contributed by the data may be so high that purchasing the data directly or contributing in-kind to ensure access may be considered. This may take the form of providing access to meta-databases, archival of data or shared maintenance. These sorts of arrangements need careful consideration as they imply a legacy commitment internally to the organisation.

IP agreements will be easiest to manage if they are consistent across suppliers, and ideally Open Source. The specific nature of any licence its pros and cons are complex. A common form of licensing created originally for the arts community is Creative Commons (Creative Commons 2012) and its variants. This is a commonly used in New Zealand, UK, Russia and Australia.

Creative Commons is an enormously useful tool however, there are some questions around:-

managing attribution;

- irrevocability of distributed information under the licence;
- the ability to terminate the license where misuse of the information has occurred;
- duty of care as an executive agency;
- on- selling of unchanged material.

Many of these concerns relates to impacts on the originator of the data rather than the user, however they are considerations which can complicate use and redistribution of data. Creative Commons has been commonly used in the UK government, but more recently they have developed their own open access license agreement. The UK Meteorological Office are now using this alternate license. The Canadian Metrological Service has also taken this approach.

One of the most important considerations in dealing with external agencies is that the licence chosen is generally accepted across that nation's government. This is because a large percentage of the organisations that are likely to provide data of a desirable quality and longevity, will be government owned. Hence the licence needs to be commonly accepted if efficiencies in negotiations are to be achieved.

Secondly, the licence should have an open source or open access basis to ensure that public are not paying multiple times for taxpayer funded data.

Key requirements (Fig. 1b):

- standard open source agreement;
- priority rating on the value of the data.

#### Implementation

Once the value and the usefulness of the data have been determined in the next consideration is its accessibility. The first decision is whether the data it can be delivered reliably and efficiently. The preference is for electronic delivery in a known format. If this is not possible, then consideration may be given to the development of specific decoders; if the data is valuable enough to warrant to the cost. It is a decision that needs to be made with some caution as ongoing management of changes in codes may be expensive, and the ability to retrieve archived data compromised.

Can the data be displayed? Can you afford to develop the display? In general if it is standard AWS data this would not be a consideration, but for new technologies or measurements this may require extensive work adequately displayed and archive. The other two considerations are the archival and quality control of the data. Do we have the capacity to archive the data? Do we have sufficient information and tools for adequate quality control of data?

Individually none of these considerations is a "deal breaker", but understanding the journey of the information is critical to getting the best value out of it. Within organisations the gathering, display, archival and quality control of data may be undertaken by a variety of different areas. Decisions in any one area may have significant impacts on another. It is therefore important that throughout this process but particularly at implementation all areas are consulted and informed.

Key information needs (Fig. 1c):

- the format, volumes and information content of the data;
- estimates of communications costs;
- estimates of integration costs including quality control, display and archival.

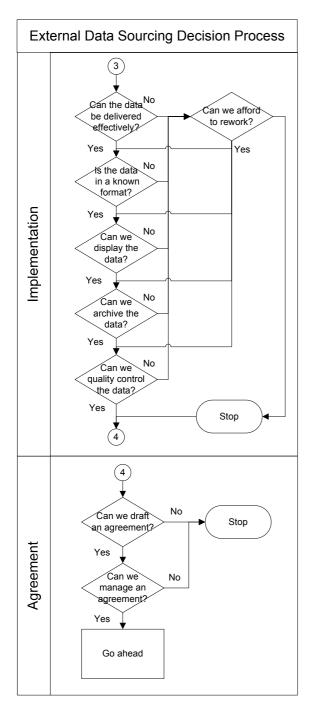


Figure 1c. External data is sourcing decision process flow diagram – Implementation and Agreement.

#### **Agreement**

This is the point at which everything comes together. We should by this stage have an understanding of:-

- what value the data can deliver;
- what priority it has for operations;
- if you can access and maintain the associated information (metadata);
- whether you have the right to use the data in the way we want;

#### CBS ET-AWS-7, Annex V, p 8

- whether in practice, you can manage the data flow and quality;
- whether you can manage the relationship in a positive and productive manner;
- what in-kind commitments are needed;
- what the general cost of incorporating the data is;
- the likely reliability and longevity of the relationship and the data supply.

If at any point along this chain the answer is a considered no, then the value of the data source must be questioned and hence any investment should be carefully considered (Fig. 1c).

It is important that both parties understand the mutual commitments and the impacts this will have on each party. Most importantly the agreement should include review points and renewal to ensure regular contact between the organisation and the supplier to maintain a healthy working relationship.

External data are not free data. There is a lot of internal work required to utilise data effectively. Every dollar invested in external data is a dollar not spent on the internal operations. While this may be valid decision, it needs to be made strategically not by process of small cuts.

### DRAFT RECOMMENDATION TO CBS-XV: REVISED FUNCTIONAL SPECIFICATIONS FOR AUTOMATIC WEATHER STATIONS

THE COMMISSION FOR BASIC SYSTEMS,

#### Noting:

- (1) The request of CBS-Ext.(06) to revise automatic weather station (AWS) functional specifications,
- (2) The Expert Team on Requirements for Data from Automatic Weather Stations (ET-AWS) Work Plan 2009-2012 to revise AWS functional specifications,

**Considering** that the AWS functional specifications have been reviewed and updated based on the inputs and proposals of other technical commissions,

**Recommends** that the revised Functional Specifications for Automatic Weather Stations (see Annex) be approved,

**Requests** the Secretary-General to make arrangements for publication of the revised functional specifications in the *Guide to the Global Observing System* (WMO-No. 488).

Annex to Recommendation No. XXX (CBS-XV)

Functional Specifications for Automatic Weather Stations

See Annex II for table.

#### Proposed ET-AWS WORKPLAN FOR THE PERIOD 2012 TO 2014

- (i) Contribute to the implementation of the WIGOS Implementation Plan (WIP) in terms of AWS networks;
- (ii) Develop standards and methods for integrating observations data (including BUFR) and metadata (static and dynamic) into WIGOS.
- (iii) Liaise with relevant ICT-IOS and ICT –ISS ETs and TTs to develop requirements for an expanded Volume A to support WIP, using WMO 488 Appendix III.3 as a basis.
- (iv) Monitor and review advances in AWS technology and networks for developed, less developed countries, and in extreme environmental conditions.
- (v) Review and update AWS Requirements and Functional Specifications, including ET-EGOS RRR database and liaison with technical experts.
- (vi) Through mutual cooperation with other ETs, develop guidance for the integration of AWS observations in support of other observing systems (e.g. space-based).
- (vii) Considering the observations and business gaps when transitioning to automated surface networks, develop guidance material suitable for NMHS. (lowest priority)

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#### ET-AWS 2012-2014

#### **Proposed TERMS OF REFERENCE**

#### **Expert Team on Requirements and Implementation of AWS Platforms (ET-AWS)**

- (a) Provide advice and support to the Chairperson of OPAG-IOS on development and implementation of WIGOS concept;
- (b) Address requirements for integration, interoperability, standardization and homogeneity of the WIGOS Implementation Plan (WIP);
- (c) Review and update the *Manual* and the *Guide on the GOS* in the context of WIP;
- (d) Address the evolution of the AWS observing networks;
- (e) Provide advice to ET-EGOS and OPAG-IOS on surface in situ contributions to the GOS to address the identified requirements and overcome known deficiencies and gaps;
- (f) Monitor advances in AWS technology.